

SHARP®

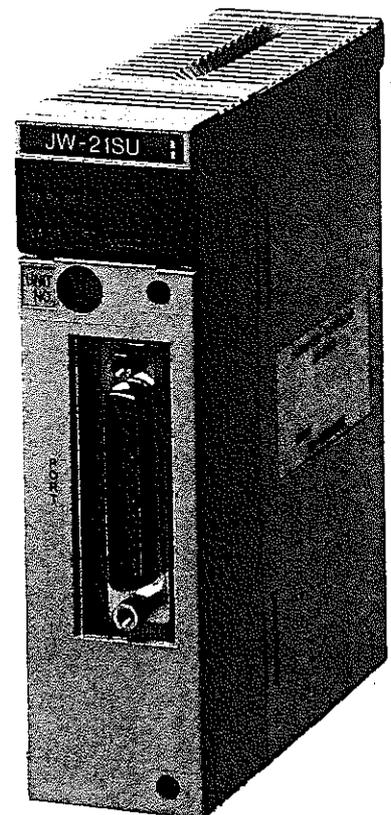
Version 2.0
Produced in Dec. 1998

Sharp Programmable Controller
New Satellite JW20H/30H

Model name

Serial interface module ***JW-21SU***

User's Manual



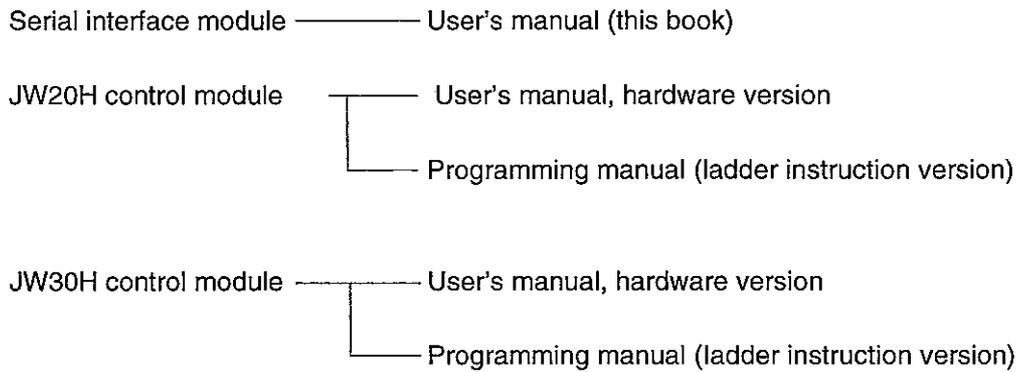
We thank you for your purchase of the serial interface module: JW-21SU for the Sharp programmable controller new satellite JW20H or JW30H.

This manual describes functions and usages of serial interface module.

Familiarize yourself with the module by reading this user's manual thoroughly.

Keep this manual with you as well as the instruction manuals attached to control module of PC. We are sure that these booklets will be helpful whenever you face a problem.

Besides this manual, the following manuals are provided further useful information.



- Should you have any questions and inquiries, feel free to contact our dealer's shop.
- Whole or partial photocopy of this booklet is prohibited.
- The contents of this booklet may be revised for improvement without notice.

Safety Precautions

Read this user's manual and attached documents carefully before installation, operation, maintenance and checking in order to use the machine correctly. Understand all of the machine knowledge, safety information, and cautions before starting to use. In this user's manual, safety precautions are ranked into "Danger" and "Caution" as follows.

 **Danger** : Wrong handling may possibly lead to death or heavy injury.

 **Caution** : Wrong handling may possibly lead to medium or light injury.

Even in the case of  **Caution**, a serious result may be experienced depending on the circumstances. Anyway, important points are mentioned. Be sure to observe them strictly.

The picture signs of prohibit and compel are explained below.

 : It means don'ts. For example, prohibition of disassembly is indicated as ().

 : It means a must. For example, obligation of grounding is indicated as ().

1) Installation

 Caution
<ul style="list-style-type: none">• Use in the environments specified in the catalog and user's manual. Electric shock, fire or malfunction may be caused when used in the environments of high temperature, high humidity, dusty or corrosive atmosphere, vibration or impact.• Install according to the instruction manual and user's manual. Wrong installation may cause drop, trouble or malfunction.• Never admit wire chips or foreign matter. Or fire, trouble or malfunction may be caused.

2) Wiring

 Compel
<ul style="list-style-type: none">• Be sure to ground. Unless grounded, electric shock or malfunction may be caused.

 Caution
<ul style="list-style-type: none">• Wiring should be done by qualified electrician. Wrong wiring may lead to fire, trouble or electric shock.

3) Use

 Danger
<ul style="list-style-type: none">• Assemble the emergency stop circuit and interlock circuit outside of the programmable controller. Otherwise the machine breakdown or accident may be caused by the trouble of the programmable controller.

 Caution
<ul style="list-style-type: none">• Manipulation for program change, forced output, RUN or STOP during operation should be done with particular care by confirming safety. Misoperation may lead to machine trouble or accident.

4) Maintenance



Prohibit

- Don't disassemble or modify.
Or fire, trouble or malfunction may be caused.



Caution

- Turn OFF the power source before detaching or attaching the module.
Or electric shock, malfunction or trouble may be caused.

Serial interface module : JW-21SU

- User's Manual -

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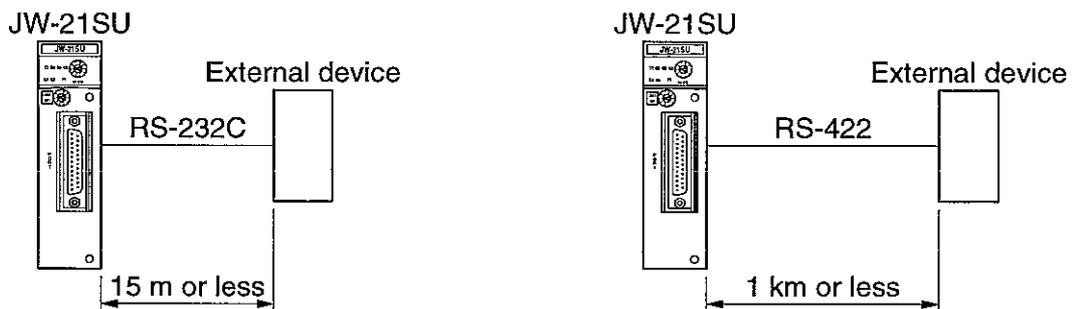
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Chapter 1. Overview

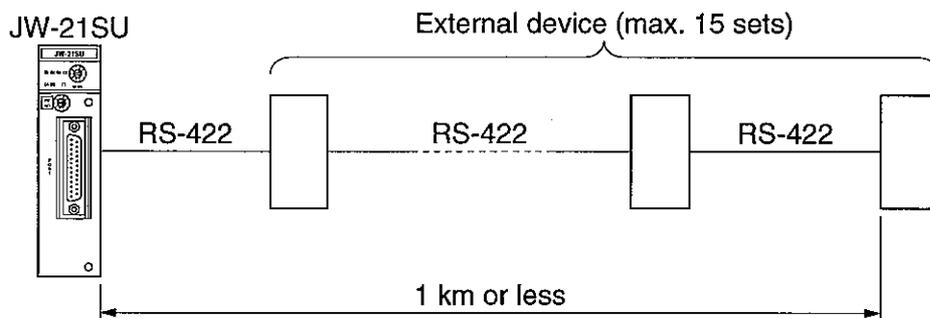
This module (JW-21SU) is a serial interface module for the programmable controller JW20H/30H and used to exchange data with the external device having RS-232C/422 interface such as host computer, satellite monitor etc.

Features and functions

(1) Either RS-232C or RS-422 is selectable as communication mode.



(2) When RS-422 is applied, max. 15 sets of external devices are connectable.



(3) Up to 8 sets in JW20H and 32 sets in JW30H for special I/O module including the others, are installable into a basic/expansion rack panel of JW20H/30H.

(4) Applicable to various data formats for exchanging data with external device.

(5) Max. 512 bytes of data sending/receiving is possible.

(6) Outputs error information by error codes.

Chapter 2. Handling Precautions

Follow the cautions below to operate and store the the module: JW-21SU.

■ Installation and storage condition

Do not install the JW-21SU in the following conditions.

- Direct sunlight, ambient temperatures below 0 °C and over +55 °C (at storage: -20 °C to +70 °C).
- Relative humidity which exceeds 35 to 90 %. Condensation due to rapid temperature variation.
- Corrosive and flammable gases.
- Vibration and shock producing and being transferred positions.

■ Combination and mounting

- In case of JW20H, make a configuration not to exceed 8 sets of modules including other special I/O module on a basic/expansion rack panel of JW20H. When more than 8 sets are installed, the JW20H will not operate.
- In case of JW30H, up to 32 sets of special I/O module including the others, are installable into only the rack No. 0 to 3 of JW30H basic/expansion rack panel. Not installable into rack No. 4 to 7.
- Unlike other special I/O module, the JW-21SU cannot be installed on a remote I/O slave station.
- Be sure to tighten retention screws of the module.

■ Wiring

- Do not run communication cables parallel or close to high voltage lines and power lines.

■ Operation

- **After install the module, be sure to execute "I/O registration" using a support tool. To operate without "I/O registration" may cause an error, and the JW20H/30H and this module don't work.**
- **In case of JW30H, if a preset scanning time is too short (less than 2 ms), JW-21SU may not function normally. To avoid this malfunction, set a longer scanning time using a constant scanning (set 3 mm or more on the system memory #226) or other functions.**
- **When setting the JW-21SU parameters, make sure to set parameter address 000 = 22_(H) and 001 = 01_(H). Without setting these addresses to these values, the JW-21SU will not be able to operate as error may occur, and the JW20H/30H and this module don't work. (See page 15 and 33.)**
- Prior to change switches inside the module, turn "OFF" power of the JW20H/30H. Switching at power "ON" may cause malfunction.
- The outside case of the module has a ventilation hole so as to prevent the inside temperature from rising. Do not block this hole or prevent ventilation.
- Be careful not to immerse in fluid such as water and chemicals or put metals such as copper wire pieces inside the module, as this is very dangerous and may cause malfunction.
- When the module is out of order or in abnormal condition (overheating, emitting a bad smell, or smoking), stop operation and contact our dealer or service center.

■ Static electricity

Excessive static electricity may be generated on the human body in extremely dry conditions. Prior to touching the module, discharge static electricity by touching grounded metals.

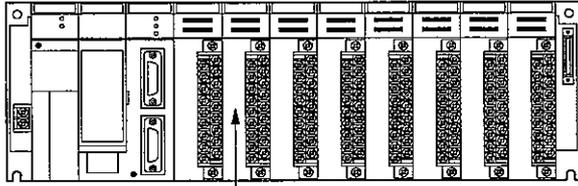
■ Cleaning

Use dry and soft cloths for cleaning. Organic solvents such as alcohol, paint thinner, and wet cloths may cause deformation or color change.

Chapter 3. System Configuration

System configuration

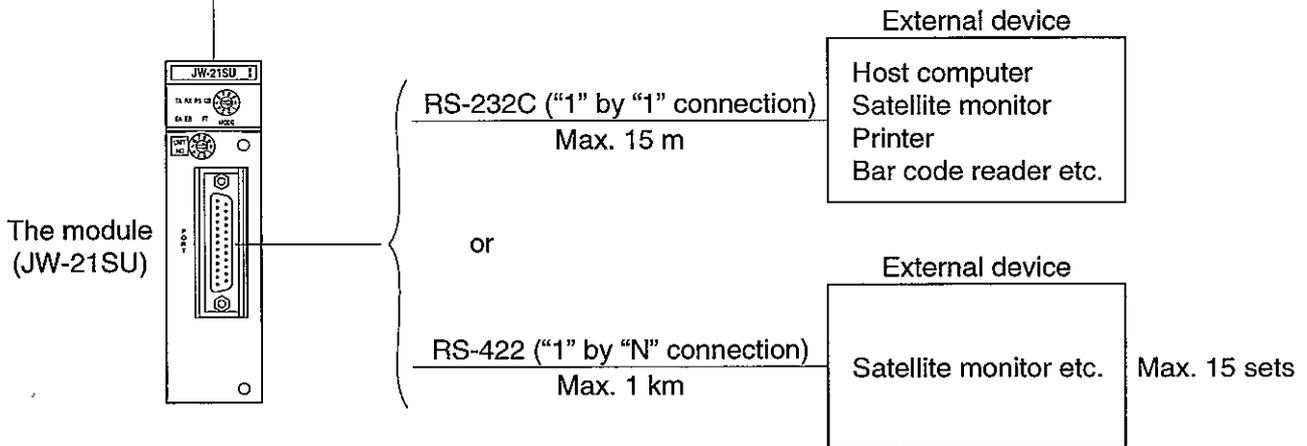
JW20H/30H



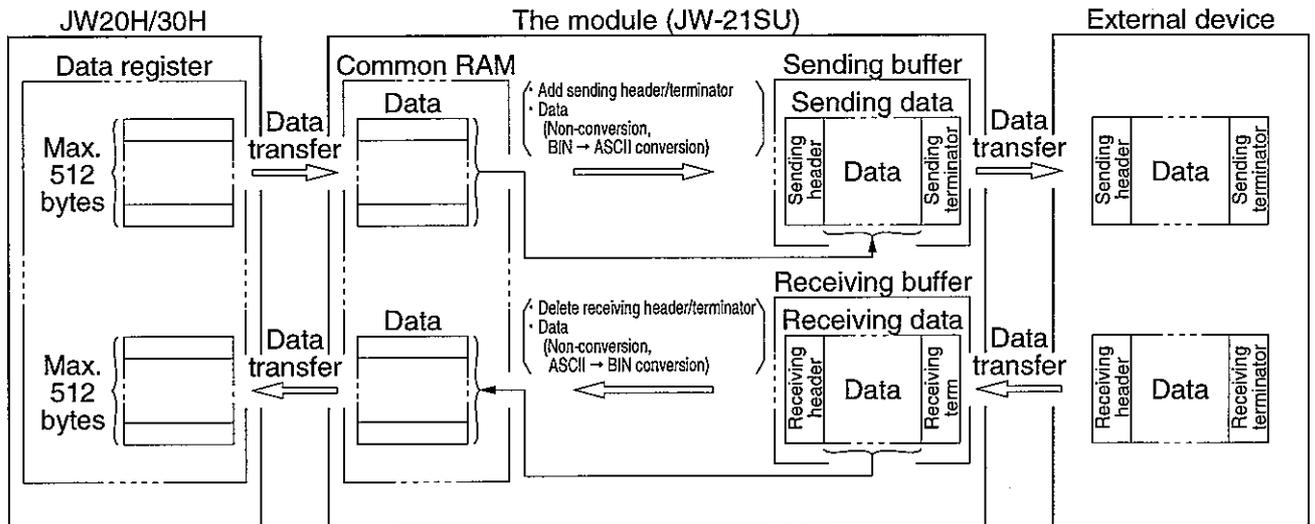
Max. no. of installed sets

JW20H	8 modules, including other special I/O modules, per basic/expansion rack panel.
JW30H	32 modules, including other special I/O modules, per basic/expansion rack panel (racks 0 to 3). · Cannot be installed in racks 4 to 7.

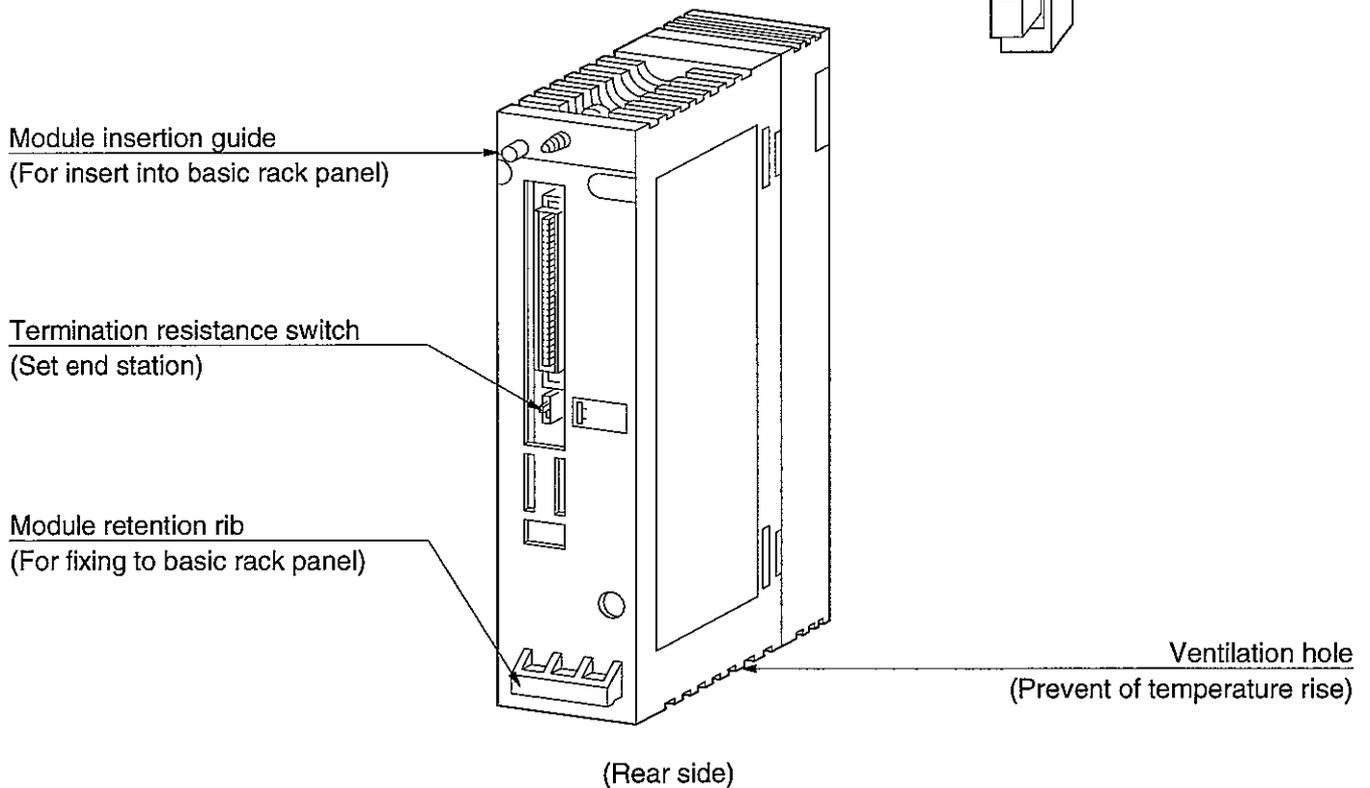
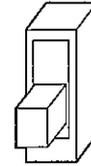
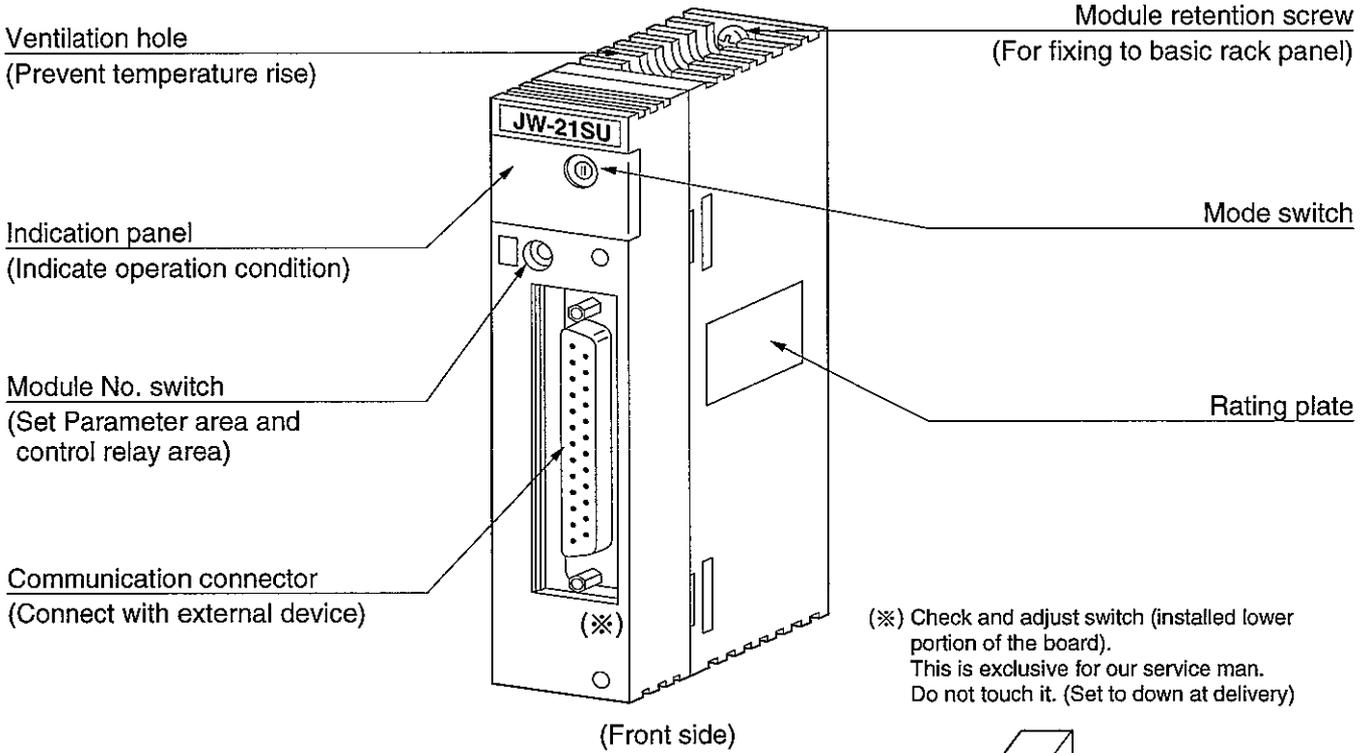
* When a JW-21SU is not installed in a remote I/O slave station (JW-21RS).



Data flow chart



Chapter 4. Name and Function of Each Part



Chapter 5. Installation

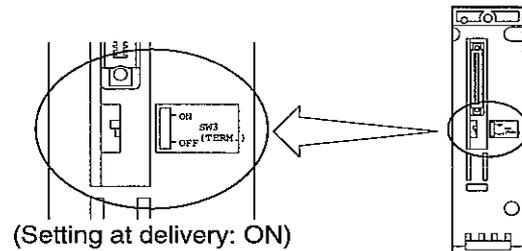
Installation procedure

(1) Turn "OFF" the power to JW20H/30H.

(2) Set the termination resistance switch [SW3 (TERM.)].

When communication mode is RS-422 (2-wire system, 4-wire system), set termination resistance. At RS-232C, this setting is not required

Setting	Condition of the module
ON	Insert termination resistance
OFF	Do not insert termination resistance

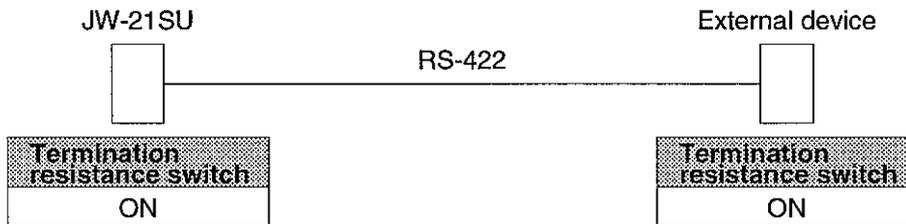


(Setting at delivery: ON)

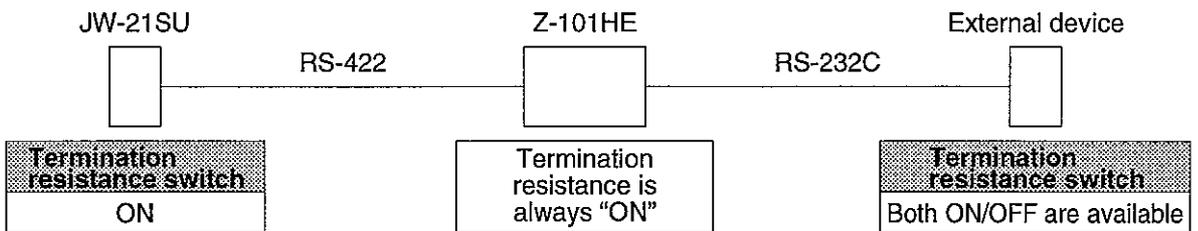
(Rear view of the module)

("1" by "1" connection)

- Turn "ON" the switch on both of the module and external device.

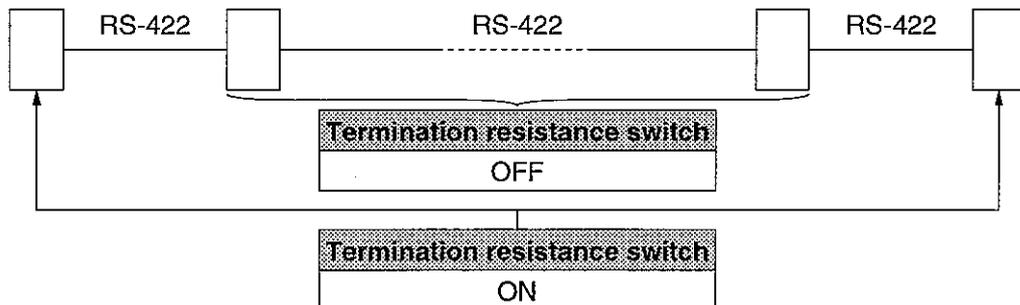


- When Z-101HE (RS-232C/RS-422 convertor) is using, termination resistance of Z-101HE is always "ON."



("1" by "N" connection)

- Turn "ON" both of end stations, turn "OFF" intermediate stations.

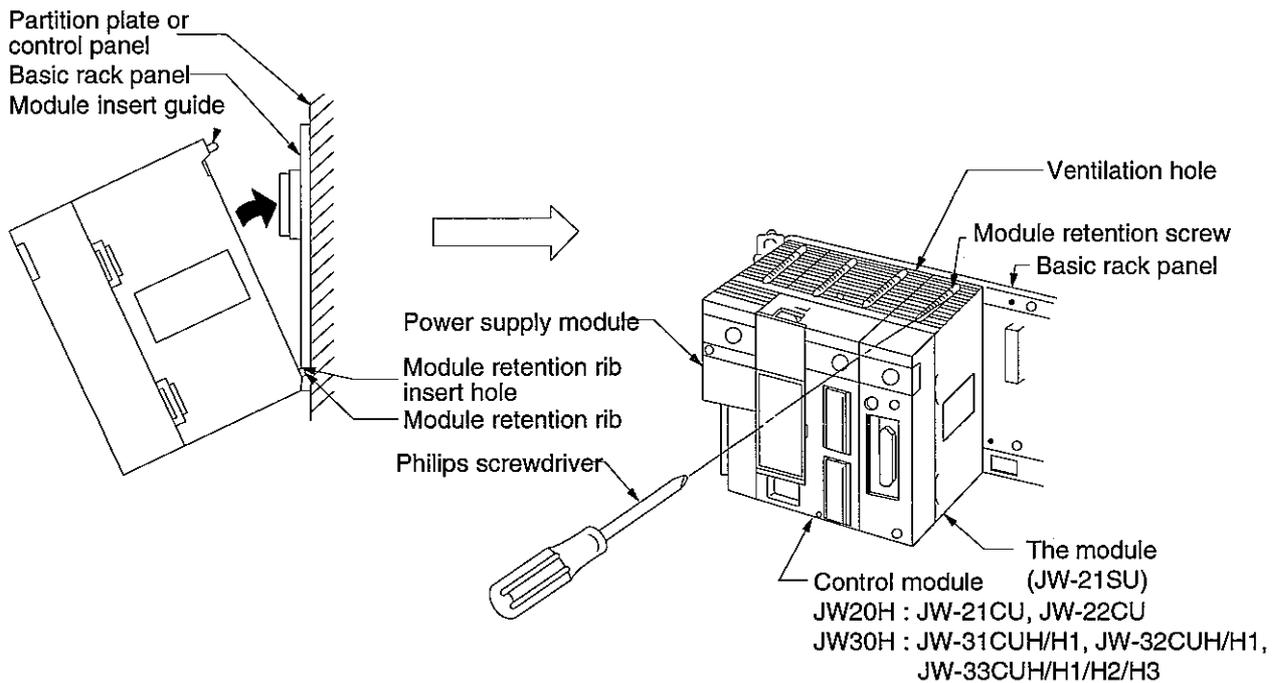


The module need not necessarily be end station.

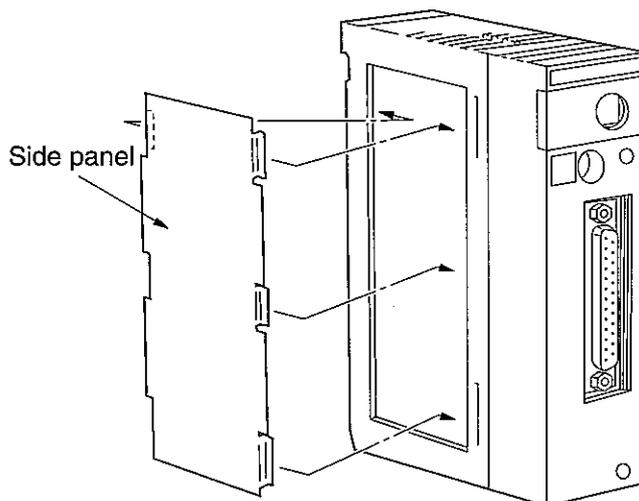
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- (3) Push the module keeping the module fixing rib hanging the insert hole on the basic rack panel.
Tighten the module retention screw at the upper side of the module using a philips screwdriver.



- Follow the same procedure to install the module on an expansion rack panel.
- Prior to install the module at left end of an expansion rack panel, be sure to fix a side plate supplied with the expansion rack panel in order to prevent dust intrusion.



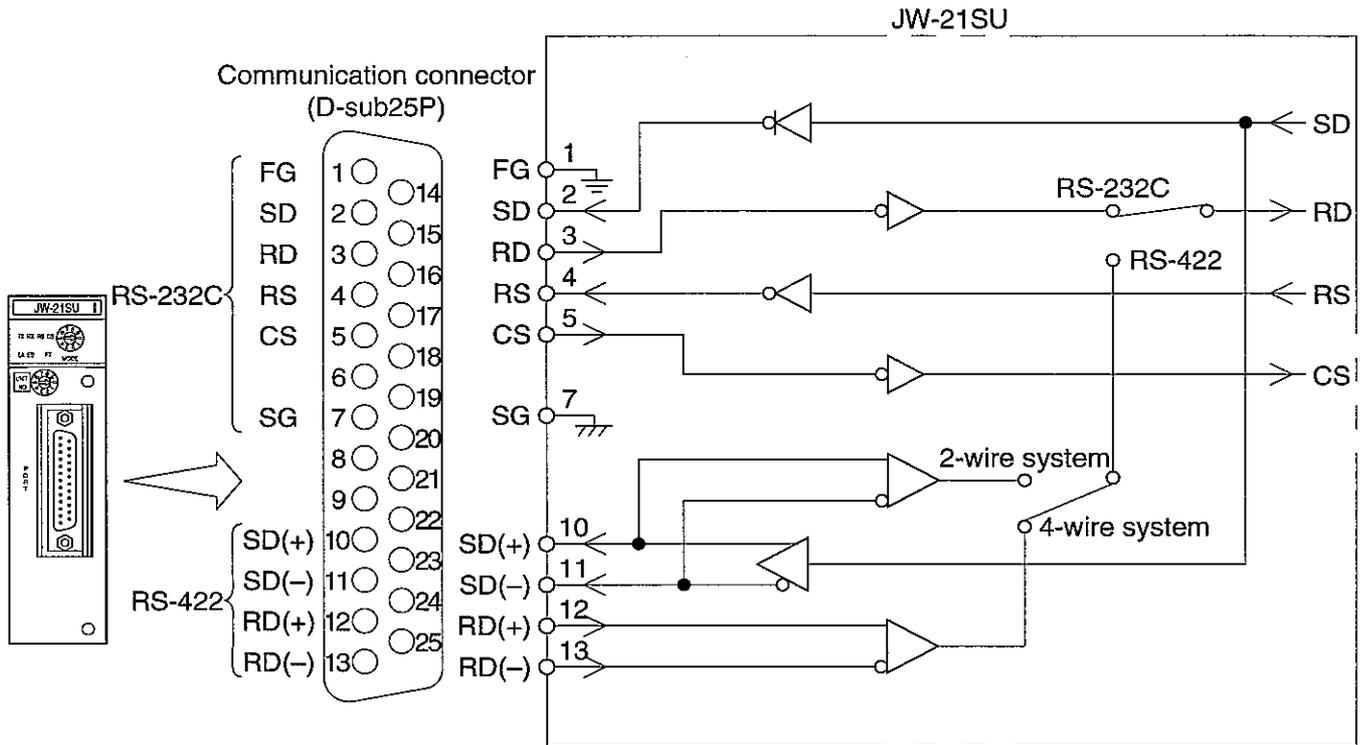
Notes

- ★ In case of JW20H, make a configuration not to exceed 8 sets of modules including other special I/O module on a basic/expansion rack panel of JW20H. In case of JW30H, up to 32 sets of special I/O module including the others, are installable into only the rack No. 0 to 3 of JW30H basic/expansion rack panel. Not installable into rack No. 4 to 7.
- ★ You can not install in remote I/O slave station of JW20H/30H.
- ★ Be sure to tighten the module retention screw. Looseness of screw may cause malfunction.

Chapter 6. Wiring

This module can connect both interface of RS-232C and RS-422 (2-wire system, 4-wire system) through a communication connector.

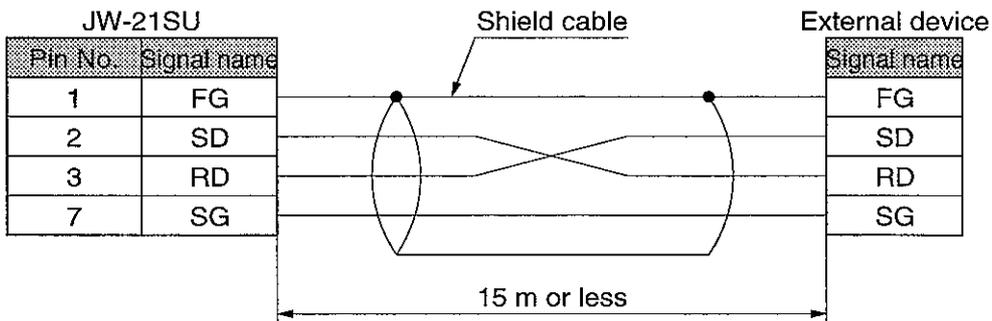
[1] Pin arrangement of communication connector



Std.	Pin No.	Signal name	Function	Signal direction
RS-232C	1	FG	Frame ground	—
	2	SD	Sending data	JW-21SU → External device
	3	RD	Receiving data	JW-21SU ← External device
	4	RS	Request to send	JW-21SU → External device
	5	CS	Ready to send	JW-21SU ← External device
	6	—	Not used	—
	7	SG	Signal ground	—
—	8, 9	—	Not used	—
RS-422	10	SD (+)	Sending signal	JW-21SU → External device
	11	SD (-)		
	12	RD (+)	Receiving signal	JW-21SU ← External device
	13	RD (-)		
—	14 to 25	—	Not used	—

[2] Connection example

(1) RS-232C (In case of control signal: absent, XON/XOFF manual, or XON/XOFF automatic)

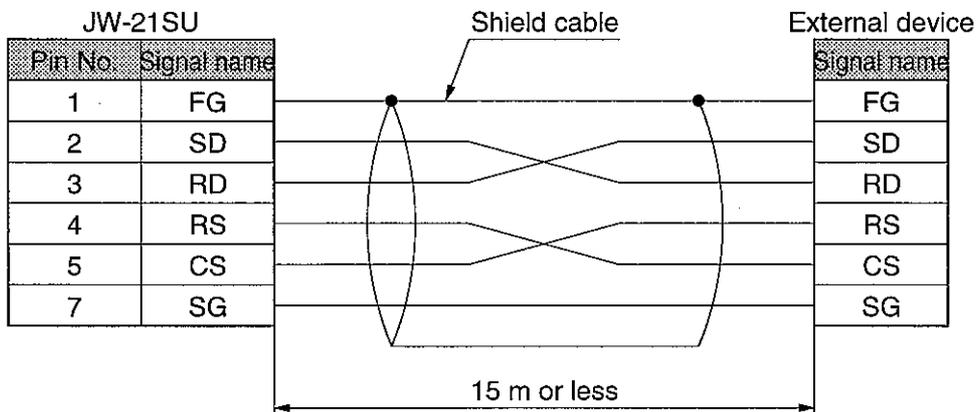


RS and CS of external device might be shorted in accordance with specification (available operation at RS, CS are "ON") of its external device.

Some external device cannot communicate unless DCD (carrier detection) is "ON".

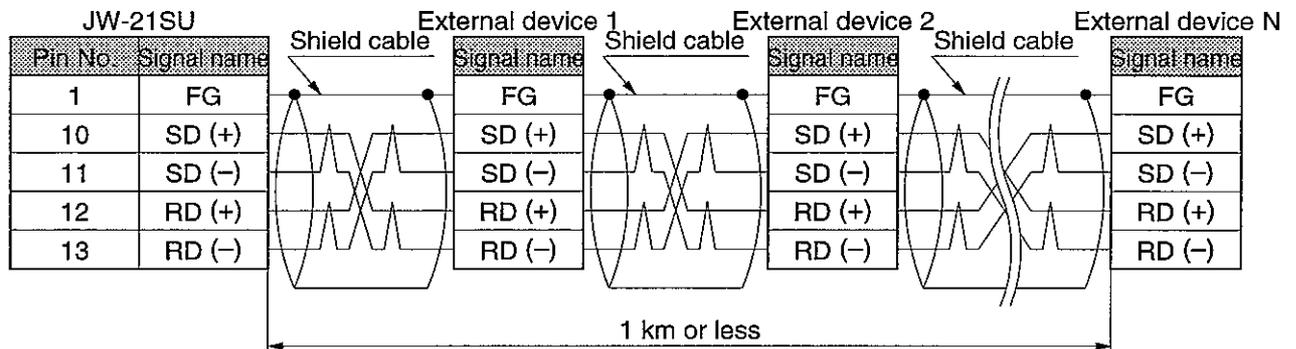
In this case, latch DCD terminal signal at the external device side or loop back "ON" voltage signal.

(2) RS-232C (In case of control signal: RS/CS manual, or RS/CS automatic)



(3) RS-422 (4-wire system)

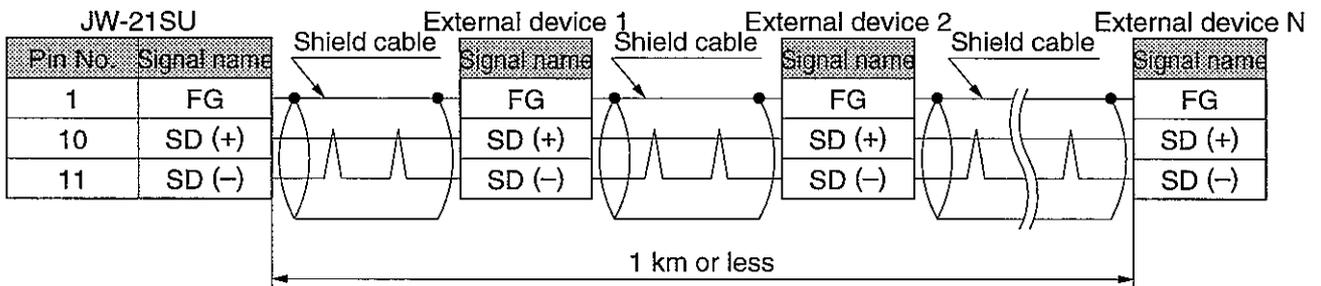
"1" by "N" connection is available. (Max. 15 sets for N)



The module need not necessarily be end station.

(4) RS-422 (2-wire system)

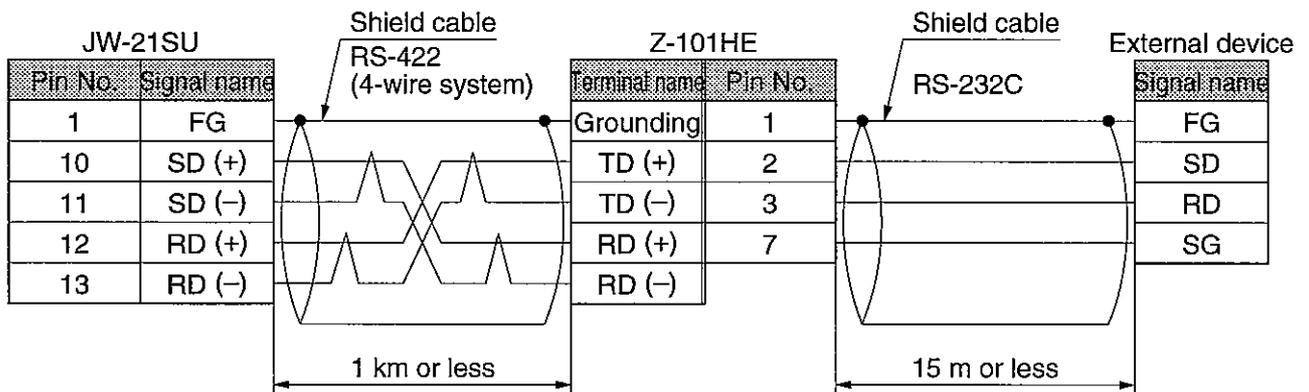
"1" by "N" connection is available. (Max. 15 sets for N)



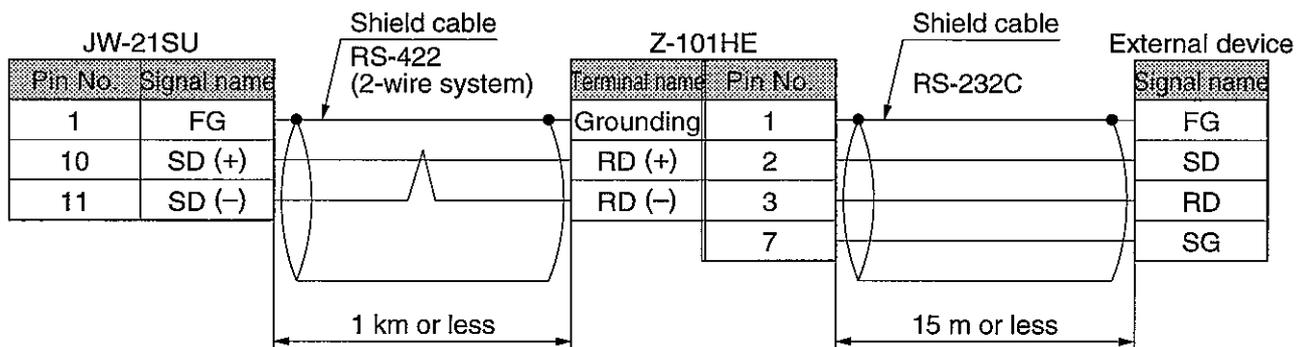
The module is not necessary to be end station.

(5) In case of using Z-101HE (RS-232C/RS-422 convertor)

1) 4-wire system



2) 2-wire system automatic



- RS and CS of external device might be shorted in accordance with specification (available operation at RS, CS are "ON") of its external device.
Some external device cannot communicate unless DCD (carrier detection) is "ON".
In this case, latch DCD terminal signal at the external device side or loop back "ON" voltage signal.
- When Z-101HE automatic mode is applied, set transfer rate 2400 bits/s or up.

Notes

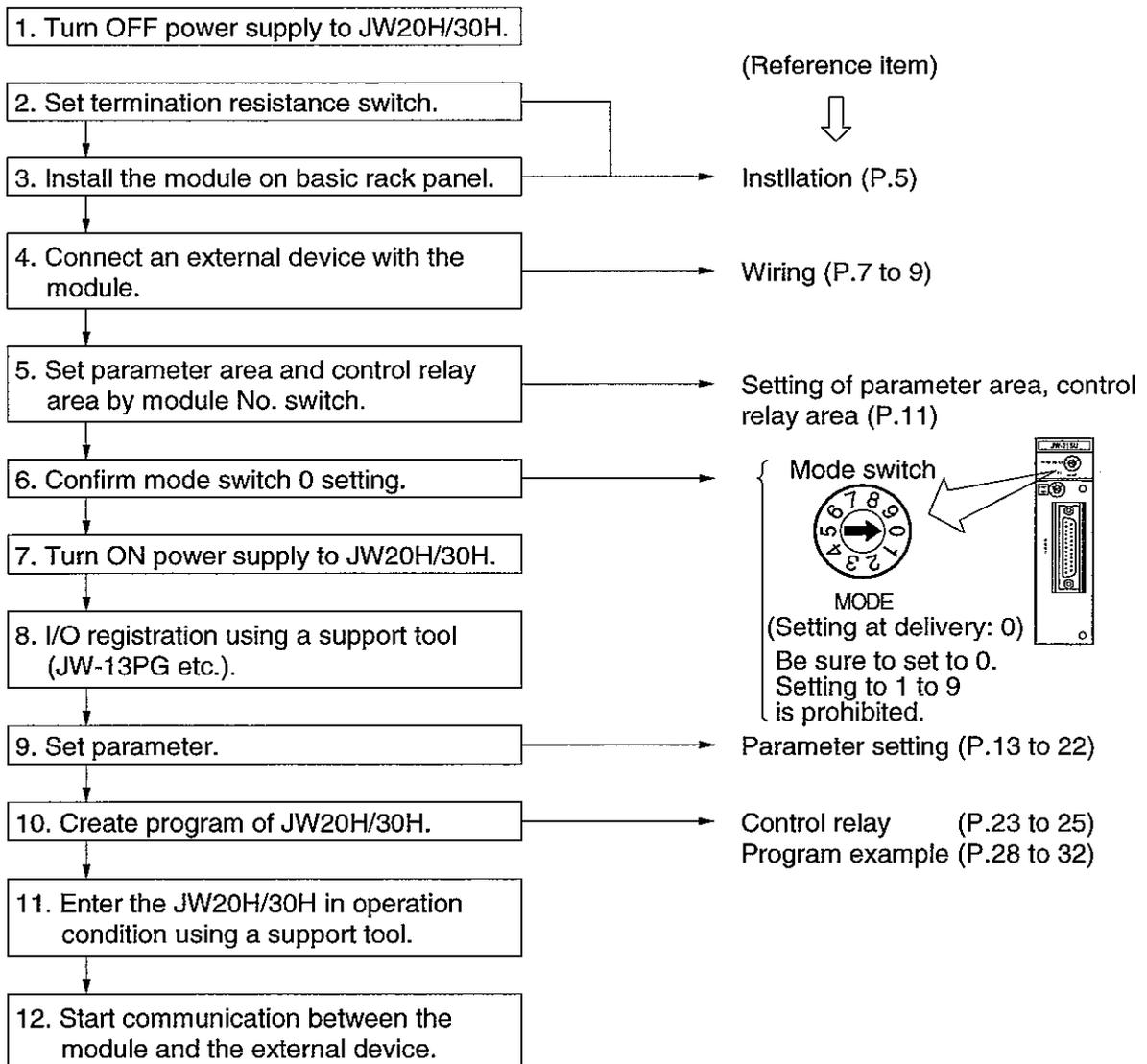
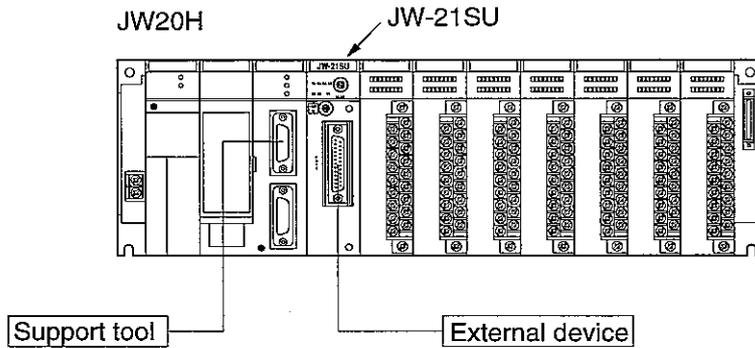
★ Be sure to use the following shielded twisted pair cables.

Manufacturer	RS-232C, RS-422 (4-wire system)	RS-422 (2-wire system)
HITACHI CABLE LTD.	CO-SPEV-SB0.5	S-IREV-SW2* 0.5

★ Wire the communication cable as far apart as possible from power lines or high voltage lines, so as not to run close parallel to them.

Chapter 7. How to Use

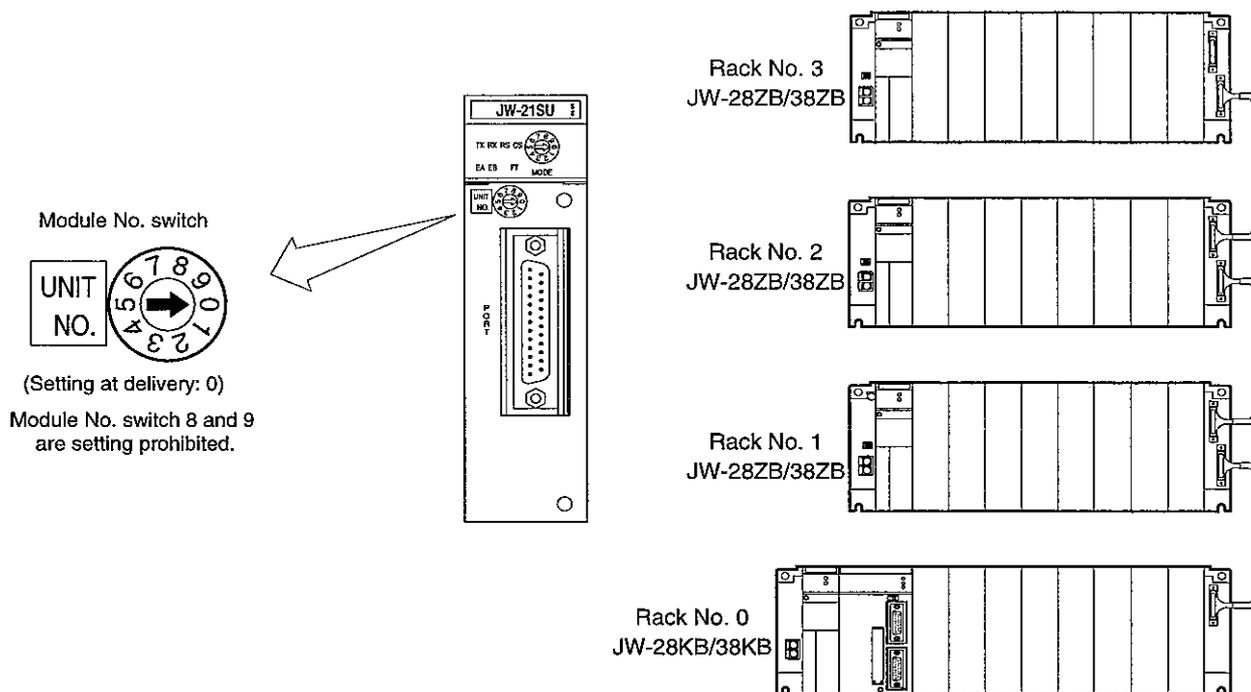
Standard operation flow is shown below. Refer to this for use.
 (Example of system configuration)



[1] Settings of parameter area, control relay area

Set parameter area to designate communication mode, transfer rate etc., and control relay area required for data sending/receiving programs using a module No. switch.

Be sure not to set same number with other special I/O module.



Note

★ Set switch when power to JW20H/30H is "OFF."

◆ In case of JW20H

The parameter area and control relay area can be set by using module No. switch of each rack.

Module No. switch setting value	Parameter area		Control relay area (byte address)	
	Parameter address	Register address of file 1		
0	T-0	000 to 177	000000 to 000177]0200 to]0217
1	T-1	000 to 177	000200 to 000377]0220 to]0237
2	T-2	000 to 177	000400 to 000577]0240 to]0257
3	T-3	000 to 177	000600 to 000777]0260 to]0277
4	T-4	000 to 177	001000 to 001177]0300 to]0317
5	T-5	000 to 177	001200 to 001377]0320 to]0337
6	T-6	000 to 177	001400 to 001577]0340 to]0357
7	T-7	000 to 177	001600 to 001777]0360 to]0377

◆ In case of JW30H

The parameter area and control relay area can be set by using module No. switch of each rack.

Module No. switch setting value	Parameter area			Control relay area (byte address)	
	Parameter address	Register address of file 1			
Rack No.0	0	T-0	000 to 177	000000 to 000177]3000 to]3017
	1	T-1	000 to 177	000200 to 000377]3020 to]3037
	2	T-2	000 to 177	000400 to 000577]3040 to]3057
	3	T-3	000 to 177	000600 to 000777]3060 to]3077
	4	T-4	000 to 177	001000 to 001177]3100 to]3117
	5	T-5	000 to 177	001200 to 001377]3120 to]3137
	6	T-6	000 to 177	001400 to 001577]3140 to]3157
	7	T-7	000 to 177	001600 to 001777]3160 to]3177
Rack No.1	0	T-0	000 to 177	002000 to 002177]3200 to]3217
	1	T-1	000 to 177	002200 to 002377]3220 to]3237
	2	T-2	000 to 177	002400 to 002577]3240 to]3257
	3	T-3	000 to 177	002600 to 002777]3260 to]3277
	4	T-4	000 to 177	003000 to 003177]3300 to]3317
	5	T-5	000 to 177	003200 to 003377]3320 to]3337
	6	T-6	000 to 177	003400 to 003577]3340 to]3357
	7	T-7	000 to 177	003600 to 003777]3360 to]3377
Rack No.2	0	T-0	000 to 177	004000 to 004177]3400 to]3417
	1	T-1	000 to 177	004200 to 004377]3420 to]3437
	2	T-2	000 to 177	004400 to 004577]3440 to]3457
	3	T-3	000 to 177	004600 to 004777]3460 to]3477
	4	T-4	000 to 177	005000 to 005177]3500 to]3517
	5	T-5	000 to 177	005200 to 005377]3520 to]3537
	6	T-6	000 to 177	005400 to 005577]3540 to]3557
	7	T-7	000 to 177	005600 to 005777]3560 to]3577
Rack No.3	0	T-0	000 to 177	006000 to 006177]3600 to]3617
	1	T-1	000 to 177	006200 to 006377]3620 to]3637
	2	T-2	000 to 177	006400 to 006577]3640 to]3657
	3	T-3	000 to 177	006600 to 006777]3660 to]3677
	4	T-4	000 to 177	007000 to 007177]3700 to]3717
	5	T-5	000 to 177	007200 to 007377]3720 to]3737
	6	T-6	000 to 177	007400 to 007577]3740 to]3757
	7	T-7	000 to 177	007600 to 007777]3760 to]3777

[2] Parameter setting

- Set the operating conditions for the JW-21SU into the JW20H/30H's parameter area.
- The support tools given below can be used to set the parameters.

Model name		Setting mode	
		When the JW20H is used	When the JW30H is used
JW-2PG		Set to parameters	Set to parameters (rack 0 only) Note 1
JW-10PG		Set in file 1	
JW-11PG		Set to parameters	—
JW-12PG		Set to parameters	Set to parameters (rack 0 only) Note 2 Set to file E Note 3
JW-13PG		Set to parameters	Set to parameters
JW-50PG	Below V4.0A	Set to parameters	Set to parameters (rack 0 only) Note 2 Set to file E Note 3
	V5.0 or up	Set to parameters	Set to parameters
Z-100LP2S + Z-3LP2EM	V5.1 or up	Set to parameters	Set to parameters (rack 0 only) Note 2
			Set to file E Note 3
JW-50SP	Below V4.0AI	Set to parameters	Set to parameters (rack 0 only) Note 2 Set to file E Note 3
	V5.0I or up	Set to parameters	Set to parameters
JW-100SP		Set to parameters	Set to parameters

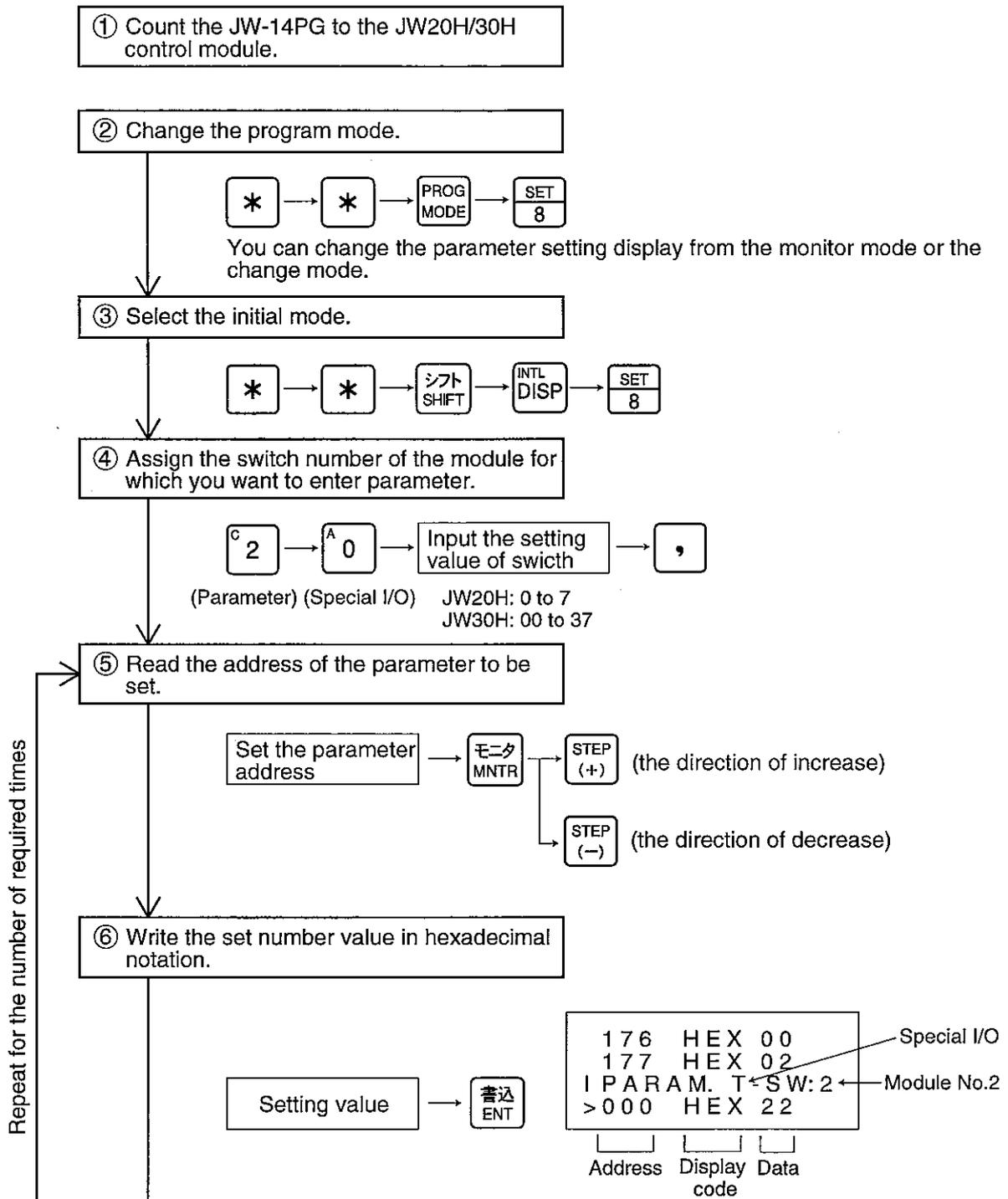
Note 1: When the JW-2PG is used with the JW30H, set the JW30H's system memory #136 = 02_(H).

Note 2: If a support tool not designed to be used with the JW30H is used, and if the JW20H specification mode is selected with the JW30H, you have to enter a different number than 50_(H) at JW30H system memory #260.

Note3: If a support tool not designed to be used with the JW30H is used, and the JW50H/70H/100H specification mode is selected with the JW30H, enter 50_(H) at JW30H system memory #260.

(1) Parameter setting procedure

- Check the installation for the JW-21SU and the settings of the module No. switch and mode select switch before the parameter area set.
- Before entering parameters, make sure the JW-21SU is in the stop (program) mode.
- These pages describe how to set parameters on an assumption that the hand-held programmer JW-14PG programmer is being used.

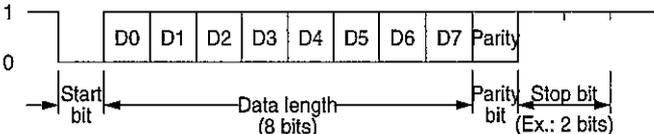
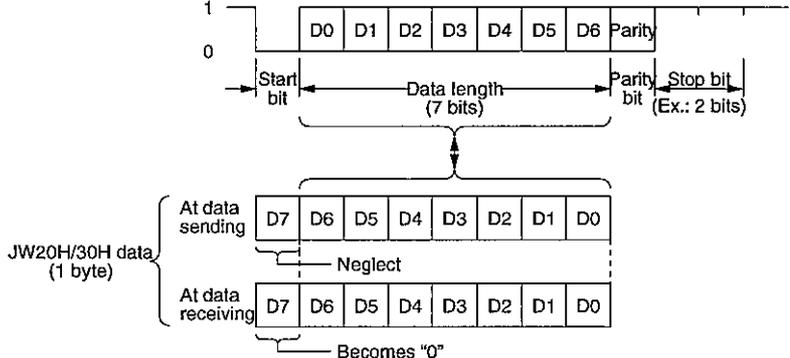


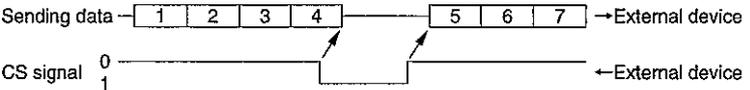
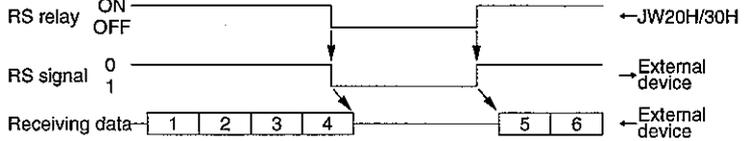
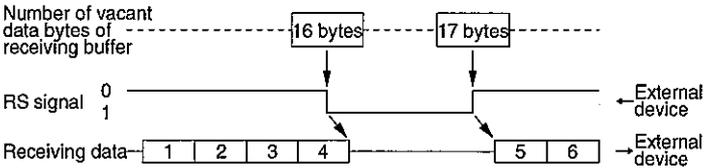
Note: Make sure to enter 22(H) and 01(H) for the parameters at address 000 and 001, respectively.

(2) Parameter setting contents

The address shown below is parameter address. In case of register address of file 1, refer to appendix 1 (P.37 to 41).

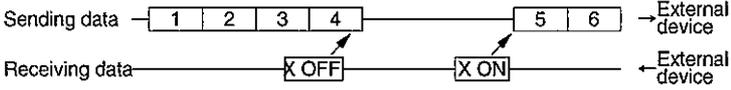
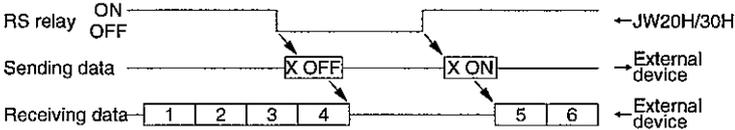
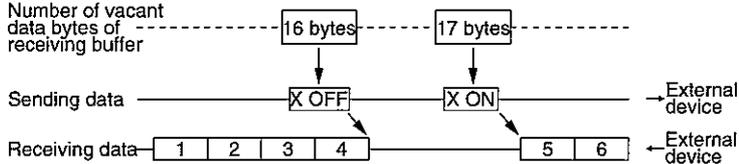
Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents	
000	Parameter transfer	22 (Initial value: 00)	Execution of parameter transfer <ul style="list-style-type: none"> When the JW20H/30H changes from "stop mode (program mode)" to "operation mode" or it turns from OFF to ON, transfer parameter from JW20H/30H memory to the module. Other than 22_{HEX} is treated as parameter transfer error. 	
001	BCC calculation	00 (Initial value)	Completion of BCC calculation	
		001	Execution of BCC calculation <ul style="list-style-type: none"> At changing parameter, set to 01_{HEX}. When the JW20H/30H changes from "stop mode (program mode)" to "operation mode" or it turns from OFF to ON, it calculates BCC codes of parameter setting contents and stores in parameter address 177. When the calculation is completed, set to 00_{HEX}. 	
002	Communi- cation mode	00 (Initial value)	RS-232C <ul style="list-style-type: none"> Transfer mode is fixed to full-duplex. 	
		01	RS-422 (4-wire system) <ul style="list-style-type: none"> Either full-duplex or half duplex is selectable as transfer mode. 	
		02	RS-422 (2-wire system) <ul style="list-style-type: none"> Transfer mode is fixed to half-duplex. 	
003	Transfer mode	00 (Initial value)	Full-duplex <ul style="list-style-type: none"> Both sending and receiving data at the same time is possible. In case of RS-422 (2-wire system), it is fixed to half-duplex so that this setting is invalid. 	
		01	Half-duplex <ul style="list-style-type: none"> Execute sending and receiving alternately. In case of RS-232C, it is fixed to full-duplex so that this setting is invalid. 	
004	Transfer speed	00 (Initial value)	19200 bits/s	<ul style="list-style-type: none"> Select to match the external device's specifications
		01	9600 bits/s	
		02	4800 bits/s	
		03	2400 bits/s	
		04	1200 bits/s	
		05	600 bits/s	

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents	
005	Data length	00 (Initial value)	<p>8 bits</p> <ul style="list-style-type: none"> Data to be subject to JIS code, binary data, special character. 	
		01	<p>7 bits</p> <ul style="list-style-type: none"> Data to be subject to ASCII code only. At communication with an external device the data length of which is fixed to 7 bits. 	
006	Stop bit	00 (Initial value)	2 bits	<ul style="list-style-type: none"> Select to match the external device's specifications
		01	1 bit	
007	Parity	00 (Initial value)	<p>Even</p> <ul style="list-style-type: none"> Set and check that length of total amount of bits of data D₀ to D₇ (D₀ to D₆ at 7 bits data length) and "ON" bit of parity bit becomes even. 	
		01	<p>Odd</p> <ul style="list-style-type: none"> Set and check that length of total amount of bits of data D₀ to D₇ (D₀ to D₆ at 7 bits data length) and "ON" bit of parity bit becomes odd. 	
		02	<p>Absent</p> <ul style="list-style-type: none"> Don't set and check above parity bit. 	

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents
010	Control signal	00 (Initial value)	<p>Absent</p> <ul style="list-style-type: none"> No check concerning communication. RS relay is normally ON.
		01	<p>RS/CS manual</p> <ul style="list-style-type: none"> Communication mode: Valid at RS-232C. Control sending data by CS signal from external device. <ol style="list-style-type: none"> When CS signal is 0, ready for data sending When CS signal is 1, stop data sending.  <p>Sending data: 1 2 3 4 5 6 7 → External device CS signal: 0 1 ← External device</p> <ul style="list-style-type: none"> Control receiving data by RS relay. <ol style="list-style-type: none"> When RS relay is OFF, RS signal becomes "1" and requests to stop data sending to an external device. When RS relay is "ON", RS signal becomes "0" and requests to send data to an external device. Receiving data time over error due to switch "OFF" RS relay does not occur.  <p>RS relay: ON OFF ← JW20H/30H RS signal: 0 1 ← External device Receiving data: 1 2 3 4 5 6 ← External device</p>
		02	<p>RS/CS automatic</p> <ul style="list-style-type: none"> Communication mode: Valid at RS-232C Control sending data by CS signal from external device. Contents is the same as RS/CS manual operation. Control receiving data by number of vacant data bytes of receiving buffer. <ol style="list-style-type: none"> When number of vacant data bytes becomes less than 16 bytes, RS signal turns to "1" and requests to stop sending data to an external device. When number of vacant data bytes becomes more than 17 bytes, RS signal turns to "0" and requests to send data to an external device.  <p>Number of vacant data bytes of receiving buffer: 16 bytes 17 bytes RS signal: 0 1 ← External device Receiving data: 1 2 3 4 5 6 ← External device</p>

Note

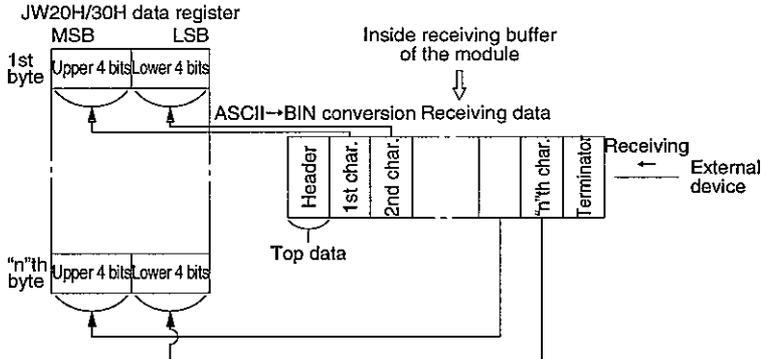
★ Match setting of control signal at external device side to the module settings.

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents
010	Control signal	03	<p>XON/XOFF manual</p> <ul style="list-style-type: none"> • Transfer mode: Valid at full-duplex. • Control sending data by XON, XOFF codes from an external device. <ol style="list-style-type: none"> 1. Possible data sending by receiving XON [11_{HEX}]. 2. Data stops sending by receiving XOFF [13_{HEX}].  <ul style="list-style-type: none"> • Control receiving data by RS relay. <ol style="list-style-type: none"> 1. The module automatically sends XOFF [13_{HEX}] by turning RS relay from "ON" to "OFF", and requests to stop sending data to an external device. 2. The module automatically sends XON [11_{HEX}] by turning RS relay from "OFF" to "ON", and requests to send data to an external device. 3. Receiving data time over error by turning OFF RS relay does not occurs. 
		04	<p>XON/XOFF automatic</p> <ul style="list-style-type: none"> • Transfer mode: Valid at full-duplex. • Control sending data by XON, XOFF codes from external device. <p>Contents is as same as XON/XOFF manual operation.</p> • Control receiving data by number of vacant data bytes of receiving buffer. <ol style="list-style-type: none"> 1. When number of vacant data bytes is less than 16 bytes, the module automatically sends XOFF [13_{HEX}] and requests to stop sending data to an external device. 2. When number of vacant data bytes is more than 17 bytes, the module automatically sends XON [11_{HEX}] and requests to send data to an external device. 

Note

★ Match setting of control signal at external device side to the Module settings.

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents
011	Transfer code conversion	00 (Initial value)	<p>Sending: Non-conversion Receiving: Non-conversion</p> <ul style="list-style-type: none"> • Send JW20H/30H's data without conversion. • Send data from an external device without conversion. • JIS codes, binary data are usable (data length: 8 bits). <p>※ Max. value of n (2 points) is 512. ※ Values in () means conditions at receiving.</p>
		01	<p>Sending: BIN → ASCII conversion Receiving: Non-conversion</p> <ul style="list-style-type: none"> • Send data after convert BIN data of JW20H/30H to ASCII form. (Sending header/terminators are sent without conversion.) • Receive data from an external device without conversion. <p>(At sending)</p> <p>※ Max. value of n (2 points) is 512.</p> <p>(At receiving) Same as receiving of setting value 00_{HEX}.</p>

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents
011	Transfer code conversion	02	<p>Sending: Non-conversion Receiving: ASCII → BIN conversion</p> <ul style="list-style-type: none"> • Send JW20H/30H's data without conversion. • After converting data from an external device as ASCII to BIN, take as JW20H/30H's data. • Only 0 to 9, A to F, ASCII characters are usable for receiving data (except receiving header, terminator). <p>(At sending) Same as sending of setting value 00_{HEX}. (See previous page)</p> <p>(At receiving)</p>  <p>※ Max. value of n (2 points) is 512. ※ Be sure to set number of receiving characters to even by an external device.</p>
		03	<p>Sending: BIN → ASCII conversion Receiving: ASCII → BIN conversion</p> <ul style="list-style-type: none"> • Send data after convert JW20H/30H's data as BIN to ASCII. (Sending header/terminators are received without conversion.) • After converting data from an external device as ASCII to BIN, take as JW20H/30H's data. • Only 0 to 9, A to F, ASCII characters are usable for receiving data (except receiving header, terminator). <p>(At sending) Same as sending of setting value 01_{HEX}. (See previous page)</p> <p>(At receiving) Same as receiving setting value 02_{HEX}.</p>

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents
012	Sending time over interval	00 (Initial value)	0 ms
		01	100 ms
		02	200 ms
		03	300 ms
		04	400 ms
		05	500 ms
		06	600 ms
		07	700 ms
		08	800 ms
		09	900 ms
		0A	1000 ms
		0B	1100 ms
		0C	1200 ms
		0D	1300 ms
		0E	1400 ms
		0F	1500 ms
		10	1600 ms
11	1700 ms		
12	1800 ms		
13	1900 ms		
14	2000 ms		
	Other than above	Setting prohibited	
013	Receiving time over interval	00 (Initial value)	0 ms
		01	100 ms
		02	200 ms
		03	300 ms
		04	400 ms
		05	500 ms
		06	600 ms
		07	700 ms
		08	800 ms
		09	900 ms
		0A	1000 ms
		0B	1100 ms
		0C	1200 ms
		0D	1300 ms
		0E	1400 ms
		0F	1500 ms
		10	1600 ms
11	1700 ms		
12	1800 ms		
13	1900 ms		
14	2000 ms		
	Other than above	Setting prohibited	

- While sending data, when data stops at a middle of 1 data frame (see page 26), the timer starts.
- When the module does not send next data until the sending time over interval, sending time out error occurs. When the module sends next data, it resets the timer and continues sending.
- Allowance of setting time is 0 to +100 ms.
(Example)
At 00_{HEX} setting: 0 ms to 100 ms
At 01_{HEX} setting: 100 ms to 200 ms

- While receiving data, when data stops at a middle of 1 data frame (see page 27), the timer starts.
- When the module does not receive next data until the receiving time over interval, receiving time out error occurs. When the module receives next data, it resets the timer and continues sending.
- Allowance of setting time is same as sending time out interval.
- When the control signal is RS/CS manual operation or XON/XOFF manual operation, and RS relay is "OFF," receiving time error does not occur.

Address T - 0 to 7	Parameter name	Setting value (Hexadecimal)	Contents																					
014 015 016 017	EXP1 header	(Initial value: 00)	<ul style="list-style-type: none"> When EXP1 header, EXP1 terminator are set at sending header/terminator or receiving header/terminator of a control relay (see page 24), the set code in this parameter is valid as control code. When NUL code [00_{HEX}] is set, thereafter set code becomes invalid so that header can use 1 to 4 characters and terminator can use 1 to 2 characters. When NUL code is set at each top address 014, 020, it becomes header: absent, terminator: absent, conditions. <p>(Setting example)</p>																					
020 021	EXP1 terminator	(Initial value: 00)	<table border="1"> <thead> <tr> <th>Address</th> <th>Setting value</th> <th>Character</th> </tr> </thead> <tbody> <tr> <td>014</td> <td>3A(H)</td> <td>:</td> </tr> <tr> <td>015</td> <td>3F(H)</td> <td>?</td> </tr> <tr> <td>016</td> <td>00(H)</td> <td>NUL</td> </tr> <tr> <td>017</td> <td>00(H)</td> <td>NUL</td> </tr> <tr> <td>020</td> <td>40(H)</td> <td>@</td> </tr> <tr> <td>021</td> <td>00(H)</td> <td>NUL</td> </tr> </tbody> </table> <p>Invalid ←</p>	Address	Setting value	Character	014	3A(H)	:	015	3F(H)	?	016	00(H)	NUL	017	00(H)	NUL	020	40(H)	@	021	00(H)	NUL
Address	Setting value	Character																						
014	3A(H)	:																						
015	3F(H)	?																						
016	00(H)	NUL																						
017	00(H)	NUL																						
020	40(H)	@																						
021	00(H)	NUL																						
022 023 024 025	EXP2 header	(Initial value: 00)	<ul style="list-style-type: none"> When EXP2 header, EXP2 terminator are set at sending header/terminator or receiving header/terminator of a control relay (see page 24), the set code in this parameter is valid as control code. 																					
026 027	EXP2 terminator	(Initial value: 00)	<ul style="list-style-type: none"> Setting contents is as same as EXP1 header, EXP1 terminator. 																					
030 to 176	Not used	(Initial value: 00)	_____																					
177	BCC code	_____	<ul style="list-style-type: none"> Setting is not required. (Setting by support tool is invalid). Store check code of parameter. (The module checks parameter setting values from JW20H/30H with this code.) 																					

[3] Control relay

Control relays are used for a program to send and receive data.

As for programming, refer to “Basic program” on Chapter 8 “Program Example” (P. 28).

(1) Control relay contents

Addresses show when the module No. switch setting is “0.” At settings of other numbers, refer to appendix 2 (P.42 to 46).

Address		Name of control relay	Contents
]0200 [Output]	D ₁	T _{RDY} (Ready sending operation)	<ul style="list-style-type: none"> Turn “ON” when data sending to an external device is available. When T_{RDY} relay turns from “OFF” to “ON”, the module clears error codes of control relay and recovers from error condition.
	D ₃	R _{REQ} (Request to transfer receiving data)	<ul style="list-style-type: none"> Turn “ON” when JW20H requests to send receiving data to the module. While R_{REQ} relay turns from “OFF” to “ON”, when the module has received data, it turns “ON” R_{ACK} relay. (It also clears error codes.)
	D ₅	RS (Request to send)	<ul style="list-style-type: none"> Control RS (control signal of RS-232C) from JW20H, this signal turns “ON” when requesting to send data to an external device. (RS signal voltage is +10 V.) Valid when parameter setting of control signal (P.19, P.20) is “RS/CS manual” and “XON, XOFF manual.”
]0201 [Input]	D ₁	T _{REQ} (Request to transfer sending data)	<ul style="list-style-type: none"> Turn “ON” when there is no data in sending buffer of the module.
	D ₃	R _{RDY} (Ready to transfer receiving data)	<ul style="list-style-type: none"> Turn “ON” when the module has receiving data, and ready to transfer to JW20H.
	D ₄	R _{ACK} (Ready to transfer receiving data)	<ul style="list-style-type: none"> Turn “ON” when the module has receiving data while R_{REQ} turns from “OFF” to “ON”. The module transfer receiving data to JW20H by F-85 instruction while R_{ACK} turns from “OFF” to “ON”, and turns “OFF” after completion of transfer.
	D ₅	CS (Ready sending)	<ul style="list-style-type: none"> Monitor CS (control signal of RS-232C) at JW20H, and turns “ON” when an external device is ready to receive data. (CS signal voltage is +3 to +15 V.)
	D ₇	U _{RDY} (Available operation of the module)	<ul style="list-style-type: none"> The module turns “ON” this signal when it ready to operate, and keeps “ON” condition with both of the below conditions. <ol style="list-style-type: none"> Completion of transfer parameter from JW20H to the module. Mode switch setting is “0.”
]0202 [Input]		Error code (See page 33, 34.)	<ul style="list-style-type: none"> The module converts errors which occurred inside to error code, and outputs to this address. Error code becomes 00_{HEX} (normal operation) at following conditions. <ol style="list-style-type: none"> When T_{RDY} relay turns from “OFF” to “ON”. JW20H starts operation. When more than one errors occurs, the module outputs priority error code.

Address		Name of control relay	Setting value or output value	Contents		
]0203 [Output]	D ₀ to D ₃	Receiving header/ terminator		Receiving header	Receiving terminator	<p>(Receiving data)</p>
			0 _{HEX}	Absent	Absent	
			1 _{HEX} *1	EXP1 header	EXP1 terminator	
			2 _{HEX} *1	EXP2 header	EXP2 terminator	
			3 _{HEX}	Absent	CR	
			4 _{HEX}	Absent	LF	
			5 _{HEX}	Absent	CR • LF	
			6 _{HEX}	STX	ETX	
			7 _{HEX} *2	STX	ETX + BCC (1 byte)	
			Other than above	Setting prohibited		
]0203 [Output]	D ₄ to D ₇	Sending header/ terminator		Receiving header	Receiving terminator	<p>(Receiving data)</p>
			0 _{HEX}	Absent	Absent	
			1 _{HEX} *1	EXP1 header	EXP1 terminator	
			2 _{HEX} *1	EXP2 header	EXP2 terminator	
			3 _{HEX}	Absent	CR	
			4 _{HEX}	Absent	LF	
			5 _{HEX}	Absent	CR • LF	
			6 _{HEX}	STX	ETX	
			7 _{HEX} *2	STX	ETX + BCC (1 byte)	
			Other than above	Setting prohibited		
]0204 (Lower)	No. of sending bytes	0000 _{HEX}	Variable data length	<ul style="list-style-type: none"> • Set number of byte of sending data to external device. • When number of byte is set to "variable data length," the module is unable to send at sending terminator being "absent," and automatically calculates number of sending bytes at sending terminator being "present." • As for relationship with other settings, see next page. 		
]0205 (Upper)		0001 _{HEX}	1 byte			
[Output]		to	to			
		0200 _{HEX}	512 bytes			
		Other than above	Setting prohibited			
]0206 (Lower)	No. of transfer bytes	0000 _{HEX}	0 byte	<ul style="list-style-type: none"> • Setting is not required. • After calculating number of receiving data bytes from an external device (except receiving header/terminator), the module outputs the result to this address. • As for relationship with other settings, see page 27. 		
]0207 (Upper)		to	to			
[Input]		0200 _{HEX}	512 bytes			
]0210 (Lower)	No. of receiving bytes	0000 _{HEX}	0 byte	<ul style="list-style-type: none"> • Set number of byte of receiving data to external device. • This setting is valid only when both receiving header/terminator are "absent." • As for relationship with other settings, see page 27. 		
]0211 (Upper)		to	to			
[Output]		0200 _{HEX}	512 bytes			
		Other than above	Setting prohibited			

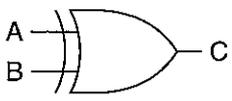
*1 (4 points) – Become parameter setted code (see page 22.)

*2 (2 points) – How to make the BCC code

BCC check is made based on the calculation of the range from STX onward up to ETX. The calculations are all performed in bit patterns of ASCII 7 bits codes.

1) Operate XOR of the first character and the second character of the communication data.

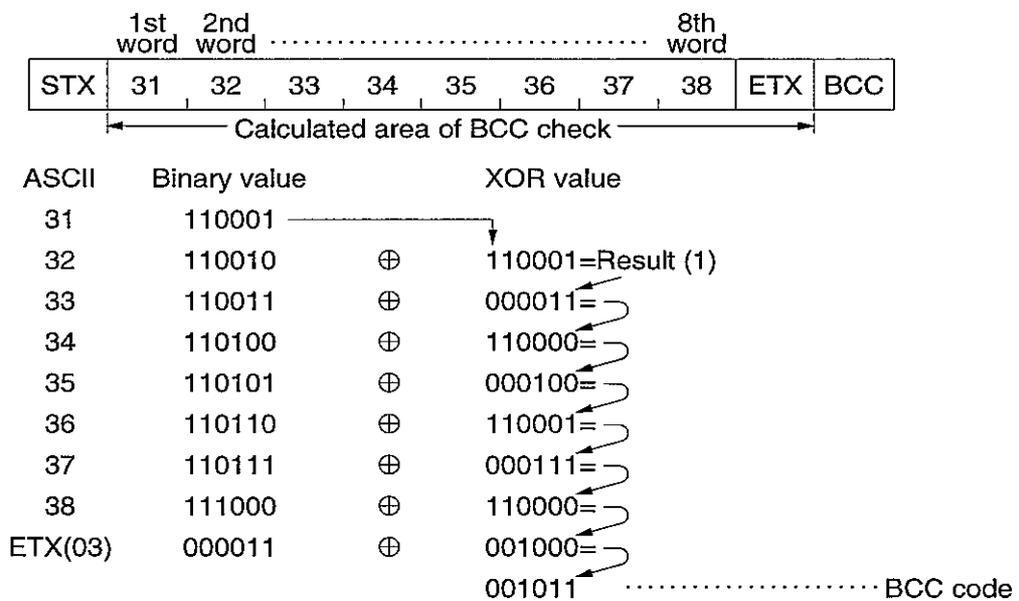
Truth table of eXclusive OR

Symbol	A	B	C
	0	0	0
	1	0	1
	0	1	1
	1	1	0

2) Operate XOR of the result of that operation and the third character.

3) Determine the result of operation sequentially and, lastly, operate XOR of ETX to take it as BCC code.

(Example)



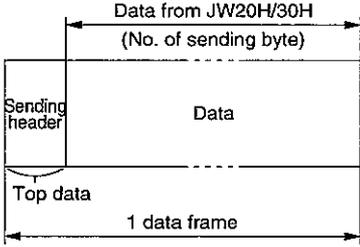
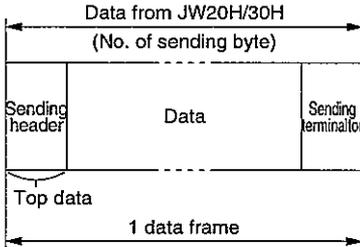
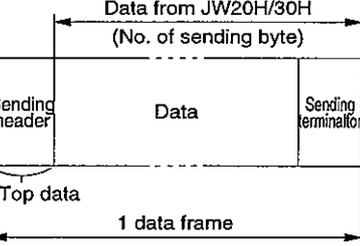
Note

★ Number of transfer bytes and receiving bytes are values after converting transfer code at data receiving. Therefore, when the module receives after conversion as ASCII to BIN (P.20), number of data bytes at an external device is 1024 bytes at max.

Number of transfer bytes. number of receiving bytes	Number of data bytes at the external device	
	Receiving: non-conversion	Receiving: ASCII → BIN conversion
1	1	2
2	2	4
to	to	to
511	511	1022
512	512	1024

[4] Sending data

Relations between sending header/terminator , number of sending bytes (P.24) and 1 data frame of sending data are as follows:

Sending terminator [Control relay setting value]	Number of sending byte [Control relay setting value]	Sending data
<p style="text-align: center;">Absent 0_{HEX}</p> <p style="text-align: center;">(Including setting EXP1 terminator or EXP2 terminator of Parameter to "absent" at 1_{HEX}, 2_{HEX} settings.)</p>	Variable data length [0000 _{HEX}]	<ul style="list-style-type: none"> Unable sending (Number of sending bytes uncertain error)
	1 to 512 bytes [0001 _{HEX} to 0200 _{HEX}]	 <p style="text-align: center;">Data from JW20H/30H (No. of sending byte)</p> <p style="text-align: center;">Data</p> <p style="text-align: center;">Sending header</p> <p style="text-align: center;">Top data</p> <p style="text-align: center;">1 data frame</p> <ul style="list-style-type: none"> Add sending header set by control relay automatically.
Present [1 _{HEX} to 7 _{HEX}]	Variable data length [0000 _{HEX}]	 <p style="text-align: center;">Data from JW20H/30H (No. of sending byte)</p> <p style="text-align: center;">Data</p> <p style="text-align: center;">Sending header</p> <p style="text-align: center;">Sending terminator</p> <p style="text-align: center;">Top data</p> <p style="text-align: center;">1 data frame</p> <ul style="list-style-type: none"> Calculate the number of sending bytes automatically. Setting sending header/terminator set in the JW20H/30H data with control relay is required.
	1 to 512 bytes [000 _{HEX} to 0200 _{HEX}]	 <p style="text-align: center;">Data from JW20H/30H (No. of sending byte)</p> <p style="text-align: center;">Data</p> <p style="text-align: center;">Sending header</p> <p style="text-align: center;">Sending terminator</p> <p style="text-align: center;">Top data</p> <p style="text-align: center;">1 data frame</p> <ul style="list-style-type: none"> Add sending header/terminator set by control relay automatically.

[5] Receiving data

Relationship between receiving header/terminator, number of receiving bytes (P.24), receiving time out interval (P.21), number of transfer bytes (P.24) with 1 data frame of receiving data are as follows:
(t_1 , t_2 are intervals between each receiving data, "T" as receiving time out interval.)

Receiving header/terminator [Control relay setting value]	Number of receiving byte [Control relay setting value]	Receiving data
Receiving header: absent Receiving terminator: absent	0 byte [0000 _{HEX}]	<p>(No. of transfer bytes)</p> <ul style="list-style-type: none"> When both t_1 and t_2 are longer than "T," an interval length between each start point of t_1 and t_2 becomes 1 data frame.
0_{HEX} (Including above conditions at 1_{HEX} , 2_{HEX} Parameter setting.)	1 ~ 512 bytes [0001 _{HEX} to 0200 _{HEX}]	<p>(No. of transfer bytes = No. of receiving bytes)</p> <ul style="list-style-type: none"> When t_1 is longer than "T," an interval of number of receiving bytes becomes 1 data frame. When t_2 becomes passed "T" set time, the Module treats it as receiving time out error and rejects received data.
Receiving header: absent Receiving terminator: present	Setting value: Invalid	<p>(No. of transfer bytes)</p> <p>1 data frame</p> <ul style="list-style-type: none"> An interval after receipt of terminator to receipt of next terminator becomes 1 data frame. *
3_{HEX} to 5_{HEX} (Including above conditions at 1_{HEX} , 2_{HEX} Parameter setting.)	Setting value: Invalid	<p>(No. of transfer bytes)</p> <p>1 data frame</p> <ul style="list-style-type: none"> An interval after receipt of terminator to receipt of next terminator becomes 1 data frame. *
Receiving header: present Receiving terminator: absent	0 byte [0000 _{HEX}]	<p>(No. of transfer bytes)</p> <p>1 data frame</p> <ul style="list-style-type: none"> An interval from header to "T" time out of t_1 becomes 1 data frame.
Above case only with 1_{HEX} , 2_{HEX} parameter settings.	1 to 512 bytes [001 _{HEX} to 0200 _{HEX}]	<p>(No. of transfer bytes = No. of receiving bytes)</p> <p>1 data frame</p> <ul style="list-style-type: none"> An interval from header to number of receiving bytes becomes 1 data frame. *
Receiving header: present Receiving terminator: present	Setting value: Invalid	<p>(No. of transfer bytes)</p> <p>1 data frame</p> <ul style="list-style-type: none"> An interval from header to terminator becomes 1 data frame. *
1_{HEX} , 2_{HEX} 6_{HEX} , 7_{HEX}	Setting value: Invalid	<p>(No. of transfer bytes)</p> <p>1 data frame</p> <ul style="list-style-type: none"> An interval from header to terminator becomes 1 data frame. *

* (3 places) When t_1 exceeds T, it becomes receiving time out error and rejects received data.

Note

★ When number of transfer bytes exceeds 512, it becomes overflow error and rejects received data.

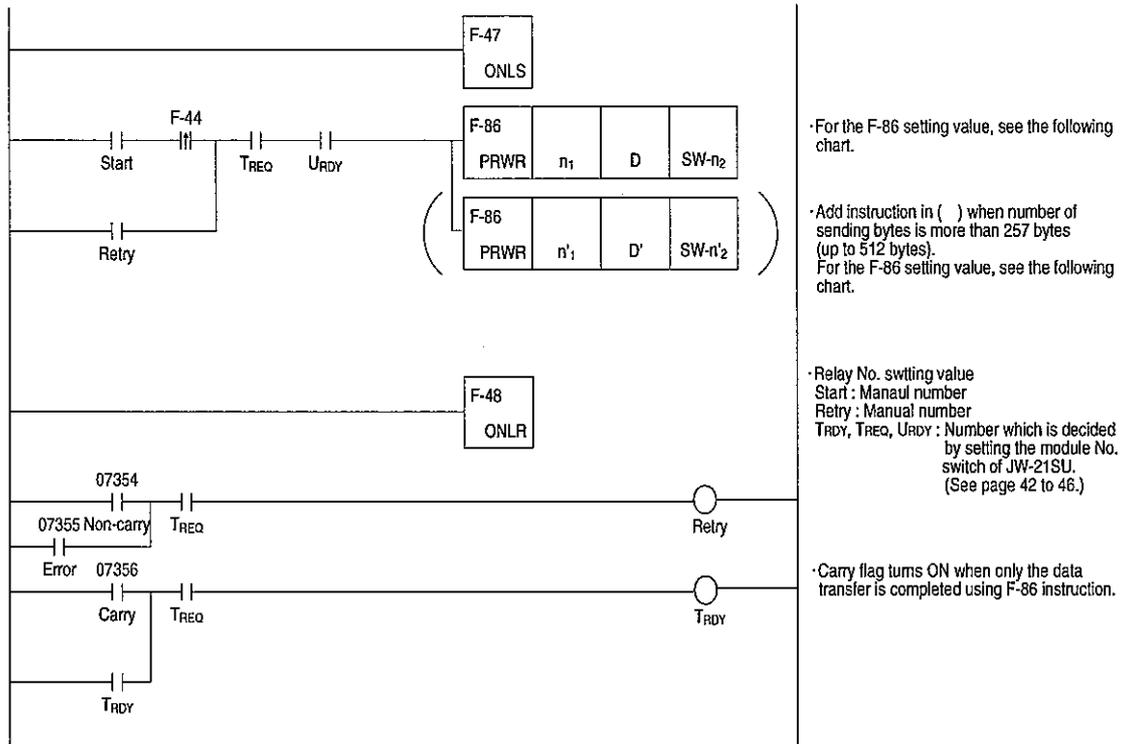
Chapter 8. Program Example

This chapter describes basic program of data sending and data receiving, and its application examples. Use this basic program for programming.

[1] Basic program

(1) Data sending

When the start relay turns from "OFF" to "ON" while there is no sending data in the module sending buffer, the module transfers JW20H/30H's data to the module's sending buffer by F-86 instruction, and starts data send to an external device. The retry relay function is capable of re-transferring data which was not executed data transfer by F-86 instruction. (As for functions of each control relay, see page 23.)

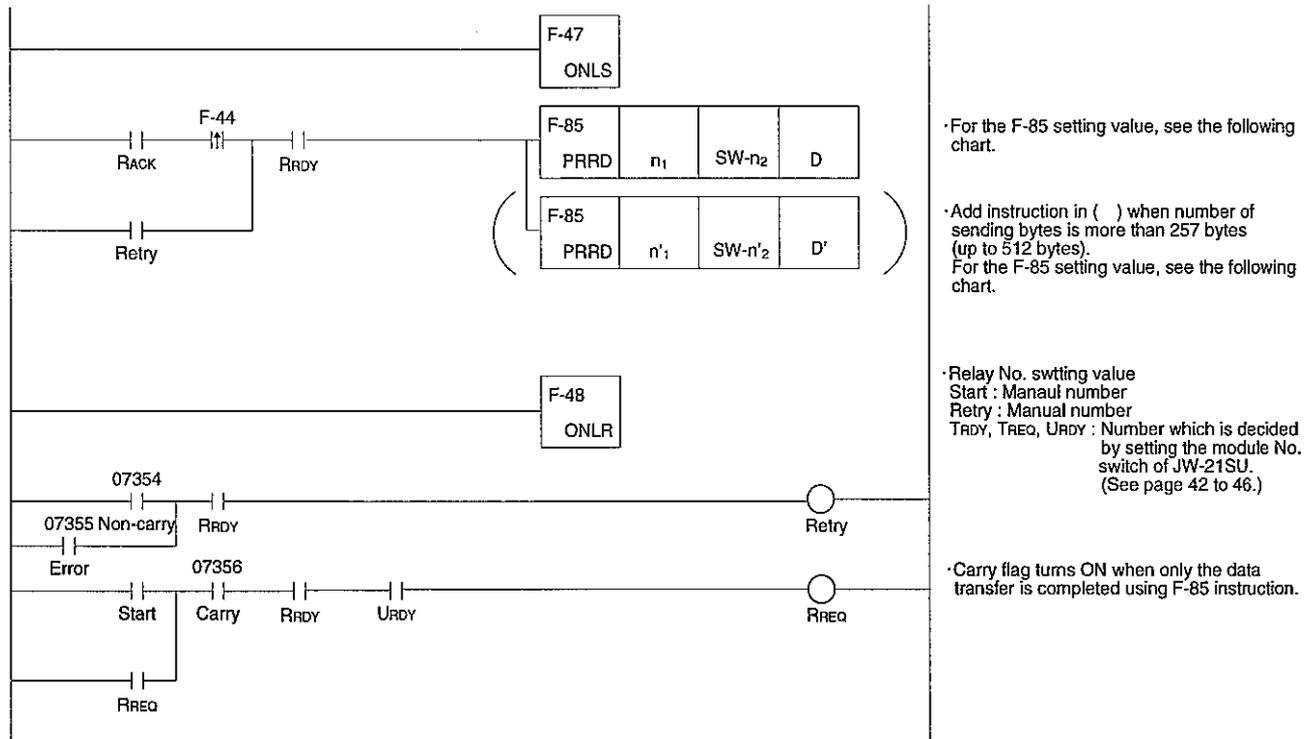


Setting value of F-86 instruction

	Number of sending bytes	
	1 to 256	257 to 512
n₁ (transfer bytes)	Set 001oct to 377oct for 257 to 511, and 000oct for 256 of number of sending bytes.	000oct
D (top address)	Set the top address of sending data JW20H :]0000 to]1577, b0000 to b1777, 09000 to 99777, E0000 to E1777 JW30H : 09000 to 99777, E0000 to E7777, file 1 000000 to 037777 @]0000 to @]1574, @]2000 to @]7574, @b0000 to @b1774, @b2000 to @b3774, @09000 to @99774, @E0000 to @E7774, file 1 @000000 to @037774	
SW (switch setting)	JW20H : 0 to 7 <module No. switch (0 to 7)> JW30H : 00 to 37 <upper digit : rack No. (0 to 3)> lower digit : module No. switch (0 to 7)>	
n₂ (transfer data)	0	0
n'₁ (number of transfer bytes)	Set 001oct to 377oct for 257 to 511, and 000oct for 512 of number of transfer bytes.	
D' (top address)	Set the 257th byte address counting from address D.	
n'₂ (transfer area)	1	

(2) Data receiving

When start relay turns from "OFF" to "ON" while there is data from an external device in the module sending buffer, the module transfers data in receiving buffer to data register of JW20H/30H by F-85 instruction. The retry relay function is capable of re-transferring data which was not executed data transfer by F-85 instruction. (As for functions of each control relay, see page 23.)



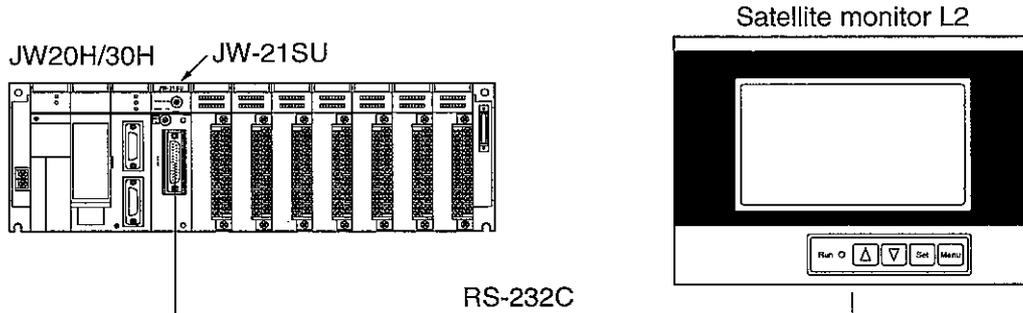
Setting value of F-85 instruction

	Number of sending bytes	
	1 to 256	257 to 512
n₁ (transfer bytes)	Set 001 _{oct} to 377 _{oct} for 257 to 511, and 000 _{oct} for 256 of number of receiving bytes.	000 _{oct}
D (top address)	Set the top address which transfer the receiving data JW20H :]0000 to]1577, b0000 to b1777, 09000 to 99777, E0000 to E1777 JW30H : 09000 to 99777, E0000 to E7777, file 1 000000 to 037777 @]0000 to @]1574, @]2000 to @]7574, @b0000 to @b1774, @b2000 to @b3774, @09000 to @99774, @E0000 to @E7774, file 1 @000000 to @037774	
SW (switch setting)	JW20H : 0 to 7 <module No. switch (0 to 7)> JW30H : 00 to 37 <upper digit : rack No. (0 to 3)> lower digit : module No. switch (0 to 7)>	
n₂ (transfer data)	2	2
n'₁ (number of transfer bytes)	Set 001 _{oct} to 377 _{oct} for 257 to 511, and 000 _{oct} for 512 of number of transfer bytes.	
D' (top address)	Set the 257th byte address counting from address D.	
n'₂ (transfer area)	3	

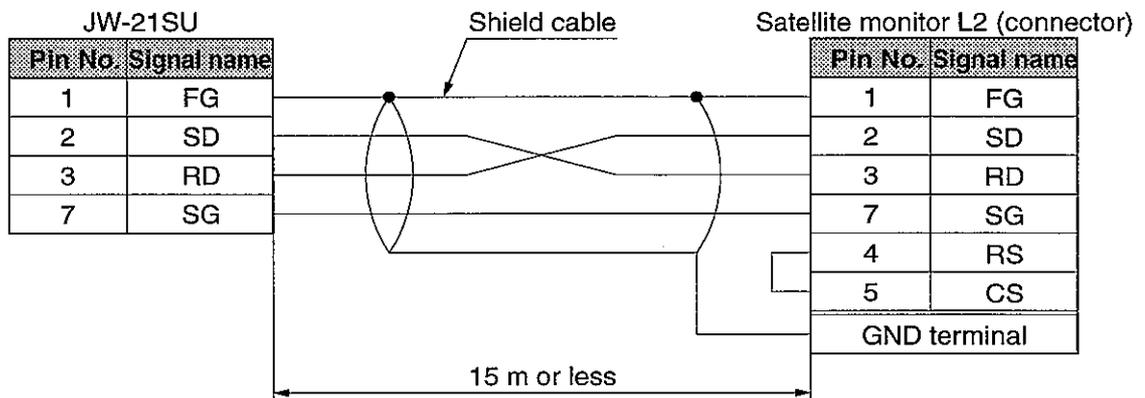
[2] Example of applied program

The example below shows how to connect satellite monitor L2 (Z-SM10) and to check screen number on L2 by JW20H.

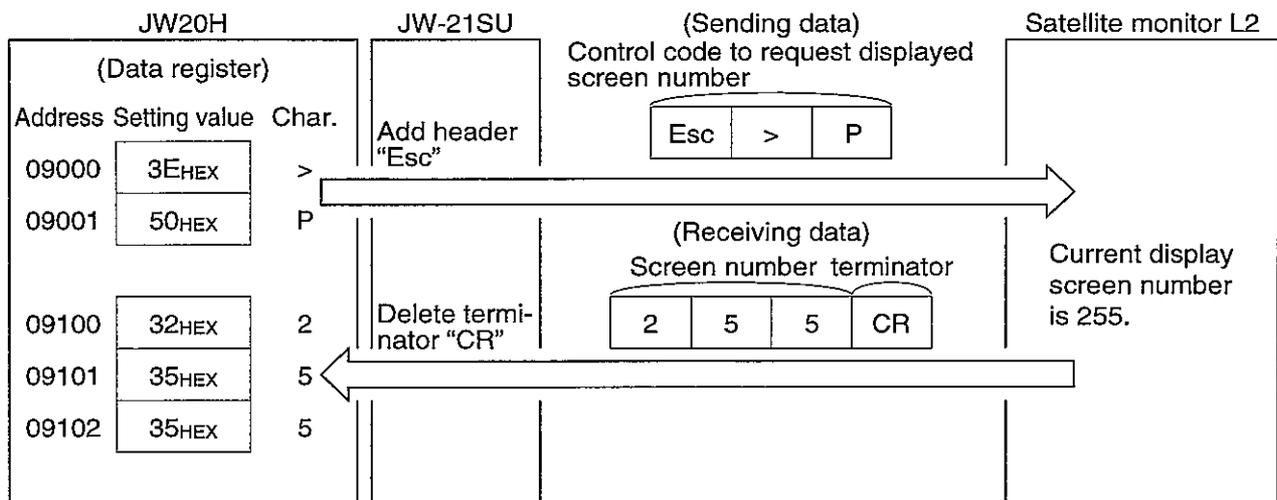
(1) System configuration



(2) Connection



(3) Data flow chart



(4) Settings of JW-21SU and JW20H

1. Parameter address and control relay address

Set module number switch as "0." With this setting, each address will be fixed. (See page 37 and 42.)

Other relay allocation

Relay name	Relay number
Start	04000 (for sending)
	04100 (for receiving)
Retry	04001 (for sending)
	04101 (for receiving)

2. Sending, receiving header/terminator setting

- Sending header: Esc, Sending terminator: absent
- Receiving header: absent, Receiving terminator: CR

Control relay setting (see page 24.)	
Address J0203 :	13 _{HEX}
[Sending header : EXP1 header]	
[Sending terminator : EXP1 terminator]	
[Receiving header : Absent]	
[Receiving terminator : CR]	

Parameter setting (see page 22.)			
	Address (T - 0)	Setting value	Char.
EXP1 header	014	1B _{HEX}	Esc
	015	00 _{HEX}	NUL
	016	00 _{HEX}	NUL
EXP1 terminator	017	00 _{HEX}	NUL
	020	00 _{HEX}	NUL
	021	00 _{HEX}	NUL

+

Set by program

Set by support tool

3. Number of sending bytes

Set 2 bytes of character ">" and "P" by program. (For details, see page 24.)

Control relay setting	
Address J0204 :	02 _{HEX} (Number of byte at lower digit)
Address J0205 :	00 _{HEX} (Number of byte at upper digit)

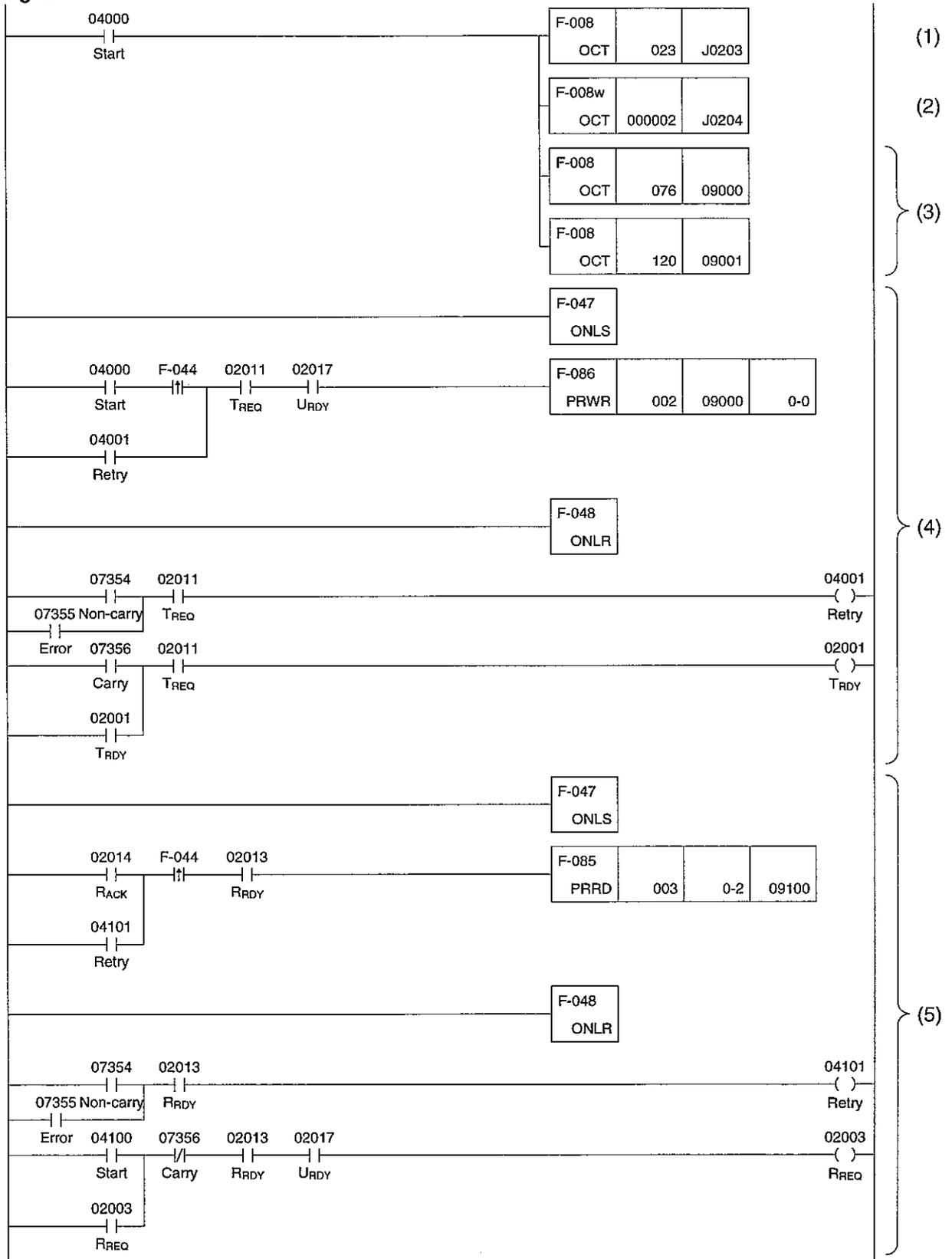
4. Number of receiving bytes

Setting is not required, because receiving header: absent, receiving terminator: present. (For details, see page 27.)

*With above, settings concerning this program has completed. Other settings are omitted.

As for satellite monitor L2 settings, see instruction manual (Chapter 12. Serial Communication mode) supplied with L2.

(5) Program



Explanation

- (1) Set sending, receiving header/terminator. [023_{OCT} = 13_{HEX}]
- (2) Set the number of sending bytes to 2 bytes. [000002_{OCT} = 0002_{HEX}]
- (3) Set character ">," "P" to register 09000, 09001 of JW20H. [076_{OCT} = 3E_{HEX}, 120_{OCT} = 50_{HEX}]
- (4) With turning start relay 04000 from "OFF" to "ON", the module sends request to display screen number to the satellite monitor L2.
- (5) With turning start relay 04100 from "OFF" to "ON", the module stores screen number received from the Satellite monitor L2 to register 09100 to 09102 of JW20H.

Chapter 9. Error and Treatment

When the module is abnormal, EA, EB, or FT on indication panel lights (see page 35), and stores error code in control relay area. (see page 23.)

The stored address is fixed by module No. switch setting of the module.

Module No. switch setting value		0	1	2	3	4	5	6	7
JW20H		J0202	J0222	J0242	J0262	J0302	J0322	J0342	J0362
JW30H	Rack No. 0	J3002	J3022	J3042	J3062	J3102	J3122	J3142	J3162
	Rack No. 1	J3202	J3222	J3242	J3262	J3302	J3322	J3342	J3362
	Rack No. 2	J3402	J3422	J3442	J3462	J3502	J3522	J3542	J3562
	Rack No. 3	J3602	J3622	J3642	J3662	J3702	J3722	J3742	J3762

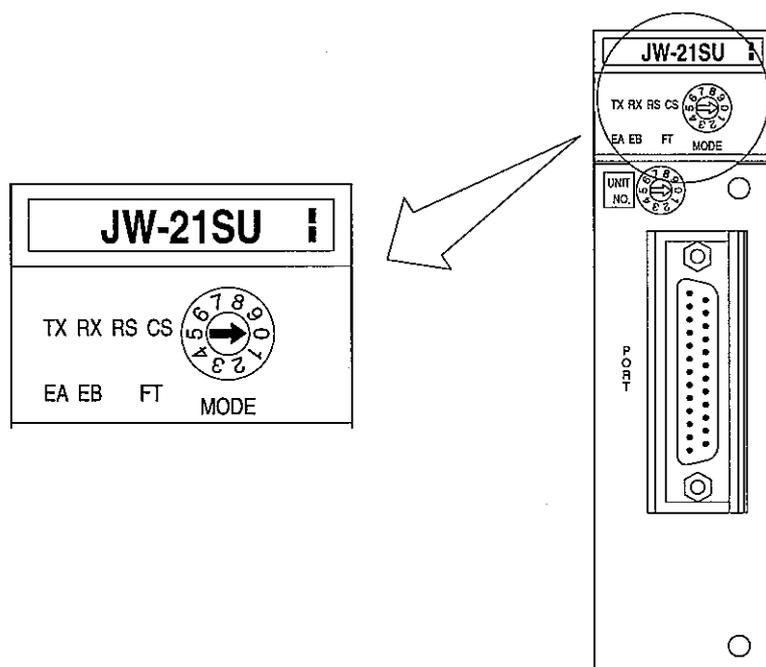
[1] Causes and treatments for errors

Error code (Hexadecimal)	Name	Cause	Treatment [() means page to refer.]	Priority	Lighting LED	
00	Normal operation	—————	—————	—	—	
Parameter setting error	80	Parameter transfer error	Set other than 22 _{HEX} in parameter transfer.	Check setting value of parameter transfer (P.15)	2	EA
	81	BCC calculation error	Setting value of BCC calculation is incorrect.	Check setting value of BCC value. (P.15)	13	
	82	Communication mode error	Setting value of communication mode is outside the range.	Check setting value of communication mode (P.15)	3	
	83	Transfer mode error	Setting value of transfer mode is outside the range.	Check setting value of transfer mode. (P.15)	4	
	84	Transfer rate error	Setting value of transfer rate is outside the range.	Check setting value of transfer rate. (P.15)	5	
	85	Data length error	Setting value of data length is outside the range.	Check setting value of data length. (P.16)	6	
	86	Stop bit error	Setting value of stop bit is outside the range.	Check setting value of stop bit. (P.16)	7	
	87	Parity error	Setting value of parity is outside the range.	Check setting value of parity. (P.16)	8	
	88	Control signal error	Setting value of control signal is outside the range.	Check setting value of control signal. (P.17, 18)	9	
	89	Transfer code conversion error	Setting value of transfer code conversion is outside the range.	Check setting value of transfer code conversion. (P.19, 20)	10	
	8A	Sending time over interval error	Setting value of sending time over interval is outside the range.	Check setting value of sending time over interval. (P.21)	11	
	8B	Receiving time over interval error	Setting value of receiving time over interval is outside the range.	Check setting value of receiving time over interval. (P.21)	12	

	Error code (Hexa- decimal)	Name	Cause	Treatment	Priority	Lighting LED
Control relay setting error	90	Sending, receiving header/terminator error	Setting value of sending, receiving header/terminator is outside the range.	Check control relay settings of sending, receiving header/terminator. (P.24)	14	EA
	91	Number of sending bytes error	<ul style="list-style-type: none"> Setting value of the number of sending bytes is outside the range. Set sending header/terminator to "absent," and number of sending byte setting is "variable data length." 	Check number of sending byte setting control relay, sending header/terminator setting control relay. (P.24)	15	
	92	Number of sending bytes undefined error	While number of sending bytes being "variable data length," there is no sending terminator in sending data.	Check sending data, sending header/terminator setting control relay, number of sending byte setting control relay, sending header/terminator setting parameter. (P.22, 24)	17	
	93	Number of receiving bytes error	Setting value of number of receiving byte is outside the range.	Check number of receiving byte setting control relay. (P.24)	16	
Communication error	A0	Parity error	Error occurs by parity check during receiving data.	<ul style="list-style-type: none"> Check communication setting with external device. Check external device, communication cable. 	19	EB
	A1	Framing error	Receiving data is abnormal.	<ul style="list-style-type: none"> Check communication setting with external device. Check external device, communication cable. 	20	
	A2	Overrun error	Receiving data exceeds receiving buffer capacity.	Check number of sending data of external device.	21	
	A3	Overflow error	Number of receiving bytes exceeds 512 bytes which is a limit to transfer to JW20H/30H.	Check number of sending data of external device.	22	
	A4	Data conversion error	Receive unable to convert code by ASCII → BIN conversion of receiving data.	Check sending data of external device.	23	
	A5	BCC check error	When receiving header/terminator is set to STX-ETX + BCC, BCC code calculated by receiving data differs from received BCC codes.	Check sending data of external device.	24	
	A6	Sending time over error	Prohibition to receive of an external device continued longer than sending time out interval set in parameter.	Check external device, communication cable.	26	
	A7	Receiving time over error	Data stopped condition while data receiving continued longer than receiving time out interval set in parameter.	Check external device, communication cable.	25	
Hardware error	C0	Hardware error	Error occurs by ROM sumcheck, RAM read/write check inside the module.	Replace the module.	1	EA
Communication error	C1	Data collision error	When the transfer mode is half-duplex, both the module and an external device send data, or communication cable is shorted.	<ul style="list-style-type: none"> Check sending, receiving timing with external device. Check communication cable. 	18	EB
	—	Module error	Watchdog timer timed over.	Replace the module.	—	FT
	—	Mode switch error	Mode switch is set to other than 0.	Set mode switch to 0.	—	EA EB

[2] Indication panel

This panel indicates operation condition of the module by LED ON/OFF.

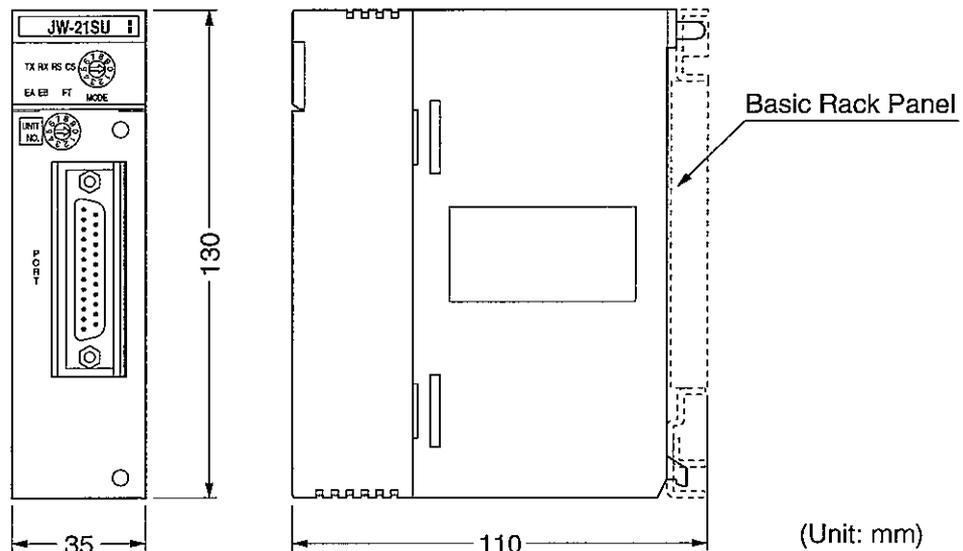


LED indication	Contents
TX	Lights while sending data (JW-21SU → external device)
RX	Lights while receiving data (JW-21SU ← external device)
RS	Lights when requesting to send data to the module from an external device.
CS	Lights when ready to send data to external device from the module.
EA	<ul style="list-style-type: none"> • Lights when parameter setting is outside the setting range. • Lights when control relay setting is outside the setting range.
EB	Lights at communication error such as parity error and time over etc.
FT	Lights at hardware error of the module.

Chapter 10. Specifications

Items	Specifications
Applicable PC	New satellite JW20H (JW21CU/22CU) JW30H (JW-31CUH/H1, JW-32CUH/H1, JW-33CUH/H1/H2/H3)
Installable slot	JW20H basic/expansion rack panel (Max. number of installed module: 8) JW30H basic/expansion rack panel (Max. number of installed module: 32)
Number of occupied I/O points	I/O relay: 16 points (dummy) Control relay: 128 points (use 8 bytes out of 16 bytes) Parameter setting: 128 bytes
Communication procedure	No protocol
Number of connectable modules	RS-232C: 1 set, RS-422: Max. 15 sets
Data transfer standard	EIA RS-232C/RS-422 (2-wire system, 4-wire system)
Transfer rate	600, 1200, 2400, 4800, 9600, 19200 bits/sec.
Synchronous mode	Start-stop system
Transfer mode	Full-duplex/half-duplex
Circuit configuration	1:1/1:N
Control signal	Absent, RS/CS manual, RS/CS automatic, XON/XOFF manual, XON/XOFF automatic
Data length	7/8 bits
Parity	Absent, odd, even
Stop bit	1/2 bits
Control character	Absent, EXP1, EXP2, CR, LF, CR • LF, STX, ETX, ETX+BCC
Transfer code	Non-conversion, BIN ↔ ASCII conversion
Number of sending/receiving bytes	Individual setting for sending/receiving (1 to 512 bytes)
Communication line	Shielded twisted pair cable Cable total length: Max. 15 m (RS-232C) Max. 1 km (RS-422)
Internal current consumption	170 mA (5 VDC)
Storage temperature	-20 to +70°C
Ambient operation temperature	0 to +55°C
Ambient humidity	35 to 90% (without dew condensation)
Vibration resistance	JIS C0911 or equivalent (same condition as JW20H/30H)
Shock resistance	JIS C0912 or equivalent (same condition as JW20H/30H)
Noise immunity	1000 Vp-p, 1μs by noise simulator
Weight	Approx. 200 g
Accessories	One instruction manual, 1 pc. of D-sub 25P connector

[Outside dimensions]



(Unit: mm)

Appendix

Appendix 1. Parameter address and parameter name

The below table shows the relation between address of parameter area and name of parameter set by module No. switches.

[1] JW20H

Parameter address	Parameter area								Parameter name
	Register address of file 1 (Setting value of module No. switch)								
	T-0 to 7	0	1	2	3	4	5	6	
000	000000	000200	000400	000600	001000	001200	001400	001600	Parameter transfer
001	000001	000201	000401	000601	001001	001201	001401	001601	BCC calculation
002	000002	000202	000402	000602	001002	001202	001402	001602	Communication mode
003	000003	000203	000403	000603	001003	001203	001403	001603	Transfer mode
004	000004	000204	000404	000604	001004	001204	001404	001604	Transfer rate
005	000005	000205	000405	000605	001005	001205	001405	001605	Data length
006	000006	000206	000406	000606	001006	001206	001406	001606	Stop bit
007	000007	000207	000407	000607	001007	001207	001407	001607	Parity
010	000010	000210	000410	000610	001010	001210	001410	001610	Control signal
011	000011	000211	000411	000611	001011	001211	001411	001611	Transfer code conversion
012	000012	000212	000412	000612	001012	001212	01412	001612	Sending time over interval
013	000013	000213	000413	000613	001013	001213	001413	001613	Receiving time over interval
014	000014	000214	000414	000614	001014	001214	001414	001614	EXP1 header
015	000015	000215	000415	000615	001015	001215	001415	001615	
016	000016	000216	000416	000616	001016	001216	001416	001616	
017	000017	000217	000417	000617	001017	001217	001417	001617	EXP1 terminator
020	000020	000220	000420	000620	001020	001220	001420	001620	
021	000021	000221	000421	000621	001021	001221	001421	001621	EXP2 header
022	000022	000222	000422	000622	001022	001222	001422	001622	
023	000023	000223	000423	000623	001023	001223	001423	001623	
024	000024	000224	000424	000624	001024	001224	001424	001624	EXP2 terminator
025	000025	000225	000425	000625	001025	001225	001425	001625	
026	000026	000226	000426	000626	001026	001226	001426	001626	Not used
027	000027	000227	000427	000627	001027	001227	001427	001627	
030 to 176	000030 to 000176	000230 to 000376	000430 to 000576	000630 to 000776	001030 to 001176	001230 to 001376	001430 to 001576	001630 to 001776	
177	000177	000377	000577	000777	001177	001377	001577	001777	BCC code

For kinds of support tools which is set by register address of parameter address and file 1, see page 13.

[2] JW30H

(1) Rack No.0

Parameter area									Parameter name
Parameter address	Register address of file E (Setting value of module No. switch)								
T-00 to 07	0	1	2	3	4	5	6	7	
000	000000	000200	000400	000600	001000	001200	001400	001600	Parameter transfer
001	000001	000201	000401	000601	001001	001201	001401	001601	BCC calculation
002	000002	000202	000402	000602	001002	001202	001402	001602	Communication mode
003	000003	000203	000403	000603	001003	001203	001403	001603	Transfer mode
004	000004	000204	000404	000604	001004	001204	001404	001604	Transfer rate
005	000005	000205	000405	000605	001005	001205	001405	001605	Data length
006	000006	000206	000406	000606	001006	001206	001406	001606	Stop bit
007	000007	000207	000407	000607	001007	001207	001407	001607	Parity
010	000010	000210	000410	000610	001010	001210	001410	001610	Control signal
011	000011	000211	000411	000611	001011	001211	001411	001611	Transfer code conversion
012	000012	000212	000412	000612	001012	001212	01412	001612	Sending time over interval
013	000013	000213	000413	000613	001013	001213	001413	001613	Receiving time over interval
014	000014	000214	000414	000614	001014	001214	001414	001614	EXP1 header
015	000015	000215	000415	000615	001015	001215	001415	001615	
016	000016	000216	000416	000616	001016	001216	001416	001616	
017	000017	000217	000417	000617	001017	001217	001417	001617	
020	000020	000220	000420	000620	001020	001220	001420	001620	EXP1 terminator
021	000021	000221	000421	000621	001021	001221	001421	001621	
022	000022	000222	000422	000622	001022	001222	001422	001622	EXP2 header
023	000023	000223	000423	000623	001023	001223	001423	001623	
024	000024	000224	000424	000624	001024	001224	001424	001624	
025	000025	000225	000425	000625	001025	001225	001425	001625	EXP2 terminator
026	000026	000226	000426	000626	001026	001226	001426	001626	
027	000027	000227	000427	000627	001027	001227	001427	001627	
030 to 176	000030 to 000176	000230 to 000376	000430 to 000576	000630 to 000776	001030 to 001176	001230 to 001376	001430 to 001576	001630 to 001776	Not used
177	000177	000377	000577	000777	001177	001377	001577	001777	BCC code

For kinds of support tools which is set by register address of parameter address and file E, see page 13.

(2) Rack No.1

Parameter address	Parameter area								Parameter name
	Register address of file E (Setting value of module No. switch)								
	T-10 to 17	0	1	2	3	4	5	6	
000	002000	002200	002400	002600	003000	003200	003400	003600	Parameter transfer
001	002001	002201	002401	002601	003001	003201	003401	003601	BCC calculation
002	002002	002202	002402	002602	003002	003202	003402	003602	Communication mode
003	002003	002203	002403	002603	003003	003203	003403	003603	Transfer mode
004	002004	002204	002404	002604	003004	003204	003404	003604	Transfer rate
005	002005	002205	002405	002605	003005	003205	003405	003605	Data length
006	002006	002206	002406	002606	003006	003206	003406	003606	Stop bit
007	002007	002207	002407	002607	003007	003207	003407	003607	Parity
010	002010	002210	002410	002610	003010	003210	003410	003610	Control signal
011	002011	002211	002411	002611	003011	003211	003411	003611	Transfer code conversion
012	002012	002212	002412	002612	003012	003212	003412	003612	Sending time over interval
013	002013	002213	002413	002613	003013	003213	003413	003613	Receiving time over interval
014	002014	002214	002414	002614	003014	003214	003414	003614	EXP1 header
015	002015	002215	002415	002615	003015	003215	003415	003615	
016	002016	002216	002416	002616	003016	003216	003416	003616	
017	002017	002217	002417	002617	003017	003217	003417	003617	
020	002020	002220	002420	002620	003020	003220	003420	003620	EXP1 terminator
021	002021	002221	002421	002621	003021	003221	003421	003621	
022	002022	002222	002422	002622	003022	003222	003422	003622	EXP2 header
023	002023	002223	002423	002623	003023	003223	003423	003623	
024	002024	002224	002424	002624	003024	003224	003424	003624	
025	002025	002225	002425	002625	003025	003225	003425	003625	EXP2 terminator
026	002026	002226	002426	002626	003026	003226	003426	003626	
027	002027	002227	002427	002627	003027	003227	003427	003627	
030 to 176	002030 to 002176	002230 to 002376	002430 to 002576	002630 to 002776	003030 to 003176	003230 to 003376	003430 to 003576	003630 to 003776	Not used
177	002177	002377	002577	002777	003177	003377	003577	003777	BCC code

For kinds of support tools which is set by register address of parameter address and file E, see page 13.

(3) Rack No.2

Parameter area									Parameter name
Parameter address	Register address of file E (Setting value of module No. switch)							T-20 to 27	
	0	1	2	3	4	5	6		
000	004000	004200	004400	004600	005000	005200	005400	005600	Parameter transfer
001	004001	004201	004401	004601	005001	005201	005401	005601	BCC calculation
002	004002	004202	004402	004602	005002	005202	005402	005602	Communication mode
003	004003	004203	004403	004603	005003	005203	005403	005603	Transfer mode
004	004004	004204	004404	004604	005004	005204	005404	005604	Transfer rate
005	004005	004205	004405	004605	005005	005205	005405	005605	Data length
006	004006	004206	004406	004606	005006	005206	005406	005606	Stop bit
007	004007	004207	004407	004607	005007	005207	005407	005607	Parity
010	004010	004210	004410	004610	005010	005210	005410	005610	Control signal
011	004011	004211	004411	004611	005011	005211	005411	005611	Transfer code conversion
012	004012	004212	004412	004612	005012	005212	005412	005612	Sending time over interval
013	004013	004213	004413	004613	005013	005213	005413	005613	Receiving time over interval
014	004014	004214	004414	004614	005014	005214	005414	005614	EXP1 header
015	004015	004215	004415	004615	005015	005215	005415	005615	
016	004016	004216	004416	004616	005016	005216	005416	005616	
017	004017	004217	004417	004617	005017	005217	005417	005617	
020	004020	004220	004420	004620	005020	005220	005420	005620	EXP1 terminator
021	004021	004221	004421	004621	005021	005221	003421	005621	
022	004022	004222	004422	004622	005022	005222	005422	005622	EXP2 header
023	004023	004223	004423	004623	005023	005223	005423	005623	
024	004024	004224	004424	004624	005024	005224	005424	005624	
025	004025	004225	004425	004625	005025	005225	005425	005625	EXP2 terminator
026	004026	004226	004426	004626	005026	005226	005426	005626	
027	004027	004227	004427	004627	005027	005227	005427	005627	
030 to 176	004030 to 004176	004230 to 004376	004430 to 004576	004630 to 004776	005030 to 005176	005230 to 005376	005430 to 005576	005630 to 005776	Not used
177	004177	004377	004577	004777	005177	005377	005577	005777	BCC code

For kinds of support tools which is set by register address of parameter address and file E, see page 13.

(4) Rack No.3

Parameter address	Parameter area								Parameter name
	Register address of file E (Setting value of module No. switch)								
	T-30 to 37	0	1	2	3	4	5	6	
000	006000	006200	006400	006600	007000	007200	007400	007600	Parameter transfer
001	006001	006201	006401	006601	007001	007201	007401	007601	BCC calculation
002	006002	006202	006402	006602	007002	007202	007402	007602	Communication mode
003	006003	006203	006403	006603	007003	007203	007403	007603	Transfer mode
004	006004	006204	006404	006604	007004	007204	007404	007604	Transfer rate
005	006005	006205	006405	006605	007005	007205	007405	007605	Data length
006	006006	006206	006406	006606	007006	007206	007406	007606	Stop bit
007	006007	006207	006407	006607	007007	007207	007407	007607	Parity
010	006010	006210	006410	006610	007010	007210	007410	007610	Control signal
011	006011	006211	006411	006611	007011	007211	007411	007611	Transfer code conversion
012	002012	006212	006412	006612	007012	007212	007412	007612	Sending time over interval
013	006013	006213	006413	006613	007013	007213	007413	007613	Receiving time over interval
014	006014	006214	006414	006614	007014	007214	007414	007614	EXP1 header
015	006015	006215	006415	006615	007015	007215	007415	007615	
016	006016	006216	006416	006616	007016	007216	007416	007616	
017	006017	006217	006417	006617	007017	007217	007417	007617	
020	006020	006220	006420	006620	007020	007220	007420	007620	EXP1 terminator
021	006021	006221	006421	006621	007021	007221	007421	007621	
022	006022	006222	006422	006622	007022	007222	007422	007622	EXP2 header
023	006023	006223	006423	006623	007023	007223	007423	007623	
024	006024	006224	006424	006624	007024	007224	007424	007624	
025	006025	006225	006425	006625	007025	007225	007425	007625	
026	006026	006226	006426	006626	007026	007226	007426	007626	EXP2 terminator
027	006027	006227	006427	006627	007027	007227	007427	007627	
030 to 176	006030 to 006176	006230 to 006376	006430 to 006576	006630 to 006776	007030 to 007176	007230 to 007376	007430 to 007576	007630 to 007776	Not used
177	006177	006377	006577	006777	007177	007377	007577	007777	BCC code

For kinds of support tools which is set by register address of parameter address and file E, see page 13.

Appendix 2. Address and name of control relay

The below table shows the relation between address of control relay area and name of control relay set by module No. switches.

[1] JW20H

Control relay address (Setting value of module No. switches)								Name of control relay (Bit address)								Signal direction
0	1	2	3	4	5	6	7	D ₁	D ₂	D ₃	D ₄	D ₅	D ₆	D ₇	D ₈	
J0200	J0220	J0240	J0260	J0300	J0320	J0340	J0360	—	—	RS	—	R _{REQ}	—	T _{RDY}	—	JW20H → JW-21SU
J0201	J0221	J0241	J0261	J0301	J0321	J0341	J0361	U _{RDY}	—	CS	R _{ACK}	R _{RDY}	—	T _{REQ}	—	JW20H ← JW-21SU
J0202	J0222	J0242	J0262	J0302	J0322	J0342	J0362	Error code								JW20H → JW-21SU
J0203	J0223	J0243	J0263	J0303	J0323	J0343	J0363	Sending header/terminator				Receiving header/terminator				
J0204	J0224	J0244	J0264	J0304	J0324	J0344	J0364	Number of sending bytes (Lower)								JW20H → JW-21SU
J0205	J0225	J0245	J0265	J0305	J0325	J0345	J0365	Number of receiving bytes (Upper)								
J0206	J0226	J0246	J0266	J0306	J0326	J0346	J0366	Number of transfer bytes (Lower)								JW20H ← JW-21SU
J0207	J0227	J0247	J0267	J0307	J0327	J0347	J0367	Number of transfer bytes (Upper)								
J0210	J0230	J0250	J0270	J0310	J0330	J0350	J0370	Number of receiving bytes (Lower)								JW20H → JW-21SU
J0211	J0231	J0251	J0271	J0311	J0331	J0351	J0371	Number of receiving bytes (Upper)								
J0212 to J0217	J0232 to J0237	J0252 to J0257	J0272 to J0277	J0312 to J0317	J0332 to J0337	J0352 to J0357	J0372 to J0377	Not used								—

[2] JW30H

(1) Rack No.0

Control relay address (Setting value of module No. switches)								Name of control relay (Bit address)								Signal direction
0	1	2	3	4	5	6	7	D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	
J3000	J3020	J3040	J3060	J3100	J3120	J3140	J3160	—	—	RS	—	R _{REQ}	—	T _{RDY}	—	JW30H → JW-21SU
J3001	J3021	J3041	J3061	J3101	J3121	J3141	J3161	U _{RDY}	—	CS	R _{ACK}	R _{RDY}	—	T _{REQ}	—	JW30H ← JW-21SU
J3002	J3022	J3042	J3062	J3102	J3122	J3142	J3162	Error code								
J3003	J3023	J3043	J3063	J3103	J3123	J3143	J3163	Sending header/terminator				Receiving header/terminator				JW30H → JW-21SU
J3004	J3024	J3044	J3064	J3104	J3124	J3144	J3164	Number of sending bytes (Lower)								
J3005	J3025	J3045	J3065	J3105	J3125	J3145	J3165	Number of receiving bytes (Upper)								
J3006	J3026	J3046	J3066	J3106	J3126	J3146	J3166	Number of transfer bytes (Lower)								JW30H ← JW-21SU
J3007	J3027	J3047	J3067	J3107	J3127	J3147	J3167	Number of transfer bytes (Upper)								
J3010	J3030	J3050	J3070	J3110	J3130	J3150	J3170	Number of receiving bytes (Lower)								JW30H → JW-21SU
J3011	J3031	J3051	J3071	J3111	J3131	J3151	J3171	Number of receiving bytes (Upper)								
J3012 to J3017	J3032 to J3037	J3052 to J3057	J3072 to J3077	J3112 to J3117	J3132 to J3137	J3152 to J3157	J3172 to J3177	Not used								—

(2) Rack No.1

Control relay address (Setting value of module No. switches)								Name of control relay (Bit address)								Signal direction
0	1	2	3	4	5	6	7	D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	
J3200	J3220	J3240	J3260	J3300	J3320	J3340	J3360	—	—	RS	—	R _{REQ}	—	T _{RDY}	—	JW30H → JW-21SU
J3201	J3221	J3241	J3261	J3301	J3321	J3341	J3361	U _{RDY}	—	CS	R _{ACK}	R _{RDY}	—	T _{REQ}	—	JW30H ← JW-21SU
J3202	J3222	J3242	J3262	J3302	J3322	J3342	J3362	Error code								JW30H → JW-21SU
J3203	J3223	J3243	J3263	J3303	J3323	J3343	J3363	Sending header/terminator				Receiving header/terminator				
J3204	J3224	J3244	J3264	J3304	J3324	J3344	J3364	Number of sending bytes (Lower)								JW30H → JW-21SU
J3205	J3225	J3245	J3265	J3305	J3325	J3345	J3365	Number of receiving bytes (Upper)								
J3206	J3226	J3246	J3266	J3306	J3326	J3346	J3366	Number of transfer bytes (Lower)								JW30H ← JW-21SU
J3207	J3227	J3247	J3267	J3307	J3327	J3347	J3367	Number of transfer bytes (Upper)								
J3210	J3230	J3050	J3270	J3310	J3330	J3350	J3370	Number of receiving bytes (Lower)								JW30H → JW-21SU
J3211	J3231	J3251	J3271	J3311	J3331	J3351	J3371	Number of receiving bytes (Upper)								
J3212 to J3217	J3232 to J3237	J3252 to J3257	J3272 to J3277	J3312 to J3317	J3332 to J3337	J3352 to J3357	J3372 to J3377	Not used								—

(3) Rack No.2

Control relay address (Setting value of module No. switches)								Name of control relay (Bit address)								Signal direction
0	1	2	3	4	5	6	7	D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	
]3400]3420]3440]3460]3500]3520]3540]3560	—	—	RS	—	R _{REQ}	—	T _{RDY}	—	JW30H → JW-21SU
]3401]3421]3441]3461]3501]3521]3541]3561	U _{RDY}	—	CS	R _{ACK}	R _{RDY}	—	T _{REQ}	—	JW30H ← JW-21SU
]3402]3422]3442]3462]3502]3522]3542]3562	Error code								
]3403]3423]3443]3463]3503]3523]3543]3563	Sending header/terminator				Receiving header/terminator				JW30H → JW-21SU
]3404]3424]3444]3464]3504]3524]3544]3564	Number of sending bytes (Lower)								
]3405]3425]3445]3465]3505]3525]3545]3565	Number of receiving bytes (Upper)								
]3406]3426]3446]3466]3506]3526]3546]3566	Number of transfer bytes (Lower)								JW30H ← JW-21SU
]3407]3427]3447]3467]3507]3527]3547]3567	Number of transfer bytes (Upper)								
]3410]3430]3450]3470]3510]3530]3550]3570	Number of receiving bytes (Lower)								JW30H → JW-21SU
]3411]3431]3451]3471]3511]3531]3551]3571	Number of receiving bytes (Upper)								
]3412 to]3417]3432 to]3437]3452 to]3457]3472 to]3477]3512 to]3517]3532 to]3537]3552 to]3557]3572 to]3577	Not used								—

(4) Rack No.3

Control relay address (Setting value of module No. switches)								Name of control relay (Bit address)								Signal direction
0	1	2	3	4	5	6	7	D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	
]3600]3620]3640]3660]3700]3720]3740]3760	—	—	RS	—	R _{REQ}	—	T _{RDY}	—	JW30H → JW-21SU
]3601]3621]3641]3661]3701]3721]3741]3761	U _{RDY}	—	CS	R _{ACK}	R _{RDY}	—	T _{REQ}	—	JW30H ← JW-21SU
]3602]3622]3642]3662]3702]3722]3742]3762	Error code								JW30H → JW-21SU
]3603]3623]3643]3663]3703]3723]3743]3763	Sending header/terminator				Receiving header/terminator				
]3604]3624]3644]3664]3704]3724]3744]3764	Number of sending bytes (Lower)								JW30H → JW-21SU
]3605]3625]3645]3665]3705]3725]3745]3765	Number of receiving bytes (Upper)								
]3606]3626]3646]3666]3706]3726]3746]3766	Number of transfer bytes (Lower)								JW30H ← JW-21SU
]3607]3627]3647]3667]3707]3727]3747]3767	Number of transfer bytes (Upper)								
]3610]3630]3650]3670]3710]3730]3750]3770	Number of receiving bytes (Lower)								JW30H → JW-21SU
]3611]3631]3651]3671]3711]3731]3751]3771	Number of receiving bytes (Upper)								
]3612 to]3617]3632 to]3637]3652 to]3657]3672 to]3677]3712 to]3717]3732 to]3737]3752 to]3757]3772 to]3777	Not used								—

Appendix 3. ASCII (JIS) code table

[1] Binary/hexadecimal

How to use ASCII code table.

Capital "A" is located in "4" of upper bit and "1" of lower bit. Thus, ASCII code of "A" is "41_{HEX}" in hexadecimal.

		Upper bit					
		0	1	2	3	4	5
Lower bit	0						
	1					A	
	2						

		Upper bit																
		Hexa-decimal	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Lower bit	Hexa-decimal	Binary	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
	0	0000	NUL	DLE	SP	0	@	P	`	p			SP	ー	タ	ミ		
	1	0001	SOH	DC1	!	1	A	Q	a	q			。	ア	チ	ム		
	2	0010	STX	DC2	／	2	B	R	b	r			「	イ	ツ	メ		
	3	0011	ETX	DC3	#	3	C	S	c	s			」	ウ	テ	モ		
	4	0100	EOT	DC4	\$	4	D	T	d	t			,	エ	ト	ヤ		
	5	0101	ENQ	NAK	%	5	E	U	e	u			・	オ	ナ	ユ		
	6	0110	ACK	SYN	&	6	F	V	f	v			ヲ	カ	ニ	ヨ		
	7	0111	BLE	ETB	^	7	G	W	g	w			ァ	キ	ヌ	ラ		
	8	1000	BS	CAN	(8	H	X	h	x			ィ	ク	ネ	リ		
	9	1001	HT	EM)	9	I	Y	i	y			ゥ	ケ	ノ	ル		
	A	1010	LF	BUS	*	:	J	Z	j	z			ヱ	コ	ハ	レ		
	B	1011	VT	ESC	+	;	K	[k	{			ォ	サ	ヒ	ロ		
	C	1100	FF	FS	,	<	L	¥	l	l			ャ	シ	フ	ワ		
	D	1101	CR	GS	-	=	M]	m	}			ュ	ス	ヘ	ン		
	E	1110	SO	RS	.	>	N	^	n	—			ョ	セ	ホ	。		
F	1111	SI	US	/	?	O	_	o	DEL			ッ	ソ	マ	。			

Note

This table only shows JIS standard and undefined parts are omitted.

[2] Octal

How to use ASCII code table.

Capital "A" is located in "10" of upper 2 digits and "1" of lower 1 digit. Thus, ASCII code of "A" is "101_{oct}" in octal.

		Upper							
		04	05	06	07	08	10	11	12
Lower	0								
	1						A		
	2								

		Upper 2 digits															
		00	01	02	03	04	05	06	07	10	11	12	13	14	15	16	17
Lower 1 digit	0	NUL	BS	DLE	CAN	SP	(0	8	@	H	P	X	`	h	p	x
	1	SOH	HT	DC1	EM	!)	1	9	A	I	Q	Y	a	i	q	y
	2	STX	LF	DC2	SUB	⋄	*	2	:	B	J	R	Z	b	j	r	z
	3	ETX	VT	DC3	ESC	#	+	3	;	C	K	S	[c	k	s	{
	4	EOT	FF	DC4	FS	\$,	4	<	D	L	T	¥	d	l	t	
	5	ENQ	CR	NAK	GS	%	-	5	=	E	M	U]	e	m	u	}
	6	ACK	SO	SYN	RS	&	.	6	>	F	N	V	^	f	n	v	~
	7	BEL	SI	ETB	US	'	/	7	?	G	O	W	_	g	o	w	DEL

		Upper 2 digits															
		20	21	22	23	24	25	26	27	30	31	32	33	34	35	36	37
Lower 1 digit	0					SP	イ	ー	ク	タ	ネ	ミ	リ				
	1					。	ウ	ア	ケ	チ	ノ	ム	ル				
	2					「	エ	イ	コ	ツ	ハ	メ	レ				
	3					」	オ	ウ	サ	テ	ヒ	モ	ロ				
	4					、	ヤ	エ	シ	ト	フ	ヤ	ワ				
	5					・	ユ	オ	ス	ナ	ヘ	ユ	ン				
	6					ヲ	ヨ	カ	セ	ニ	ホ	ヨ	。				
	7					ア	ツ	キ	ソ	ヌ	マ	ラ	。				

Note

This table only shows JIS standard and undefined parts are omitted.

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Sending signal	7		
Sending time over interval	19		
Setting value of			
Module No. switch	11, 35, 36		
Signal ground	7		
Signal name	7		
CS	7		
FG	7		
RD	7		
RD (+)	7		
RD (-)	7		
RS	7		
SD	7		

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