X20(c)DI9371

1 General Information

The module is equipped with 12 inputs for 1-wire connections. The module is designed for sink input wiring.

- · 12 digital inputs
- · Sink connection
- · 1-wire connections
- · Software input filter can be configured for entire module

2 Coated modules

Coated modules are X20 modules with a protective coating for the electronics component. This coating protects X20c modules from condensation and corrosive gases.

The modules' electronics are fully compatible with the corresponding X20 modules.

For simplification purposes, only images and module IDs of uncoated modules are used in this data sheet.

The coating has been certified according to the following standards:

- Condensation: BMW GS 95011-4, 2x 1 cycle
- Corrosive gas: EN 60068-2-60, Method 4, Exposure 21 days







3 Order data

Model number	Short description
	Digital inputs
X20DI9371	X20 digital input module, 12 inputs, 24 VDC, sink, configurable input filter, 1-wire connections
X20cDI9371	X20c digital input module, coated, 12 inputs, 24 VDC, sink, configurable input filter, 1-wire connections
	Required accessories
	Bus modules
X20BM11	X20 bus module, 24 VDC keyed, internal I/O supply continuous
X20cBM11	X20 bus module, coated, 24 VDC keyed, internal I/O supply continuous
	Terminal blocks
X20TB12	X20 terminal block, 12-pin, 24 VDC keyed

Table 1: X20DI9371, X20cDI9371 - Order data

4 Technical data

Product ID	X20DI9371 X20cDI9371
Short description	
I/O module	12 digital inputs 24 VDC for 1-wire connections
General information	
B&R ID code	0x1B95 0xD574
Status indicators	I/O function per channel, operating state, module status
Diagnostics	
Module run/error	Yes, using status LED and software
Power consumption	
Bus	0.18 W
Internal I/O	-
External I/O	1.75 W
Additional power dissipation caused by the actuators (resistive) [W]	-
Electrical isolation	
Channel - Bus	Yes
Channel - Channel	No
Certification	
CE	Yes
cULus	Yes
cCSAus HazLoc Class 1 Division 2	Yes -
ATEX Zone 2 1)	Yes
KC	Yes -
GL	Yes
GOST-R	Yes
Digital inputs	0.1./00
Nominal voltage	24 VDC
Input voltage	24 VDC -15% / +20%
Input current at 24 VDC	Typ. 3.75 mA
Input filter	,
Hardware	≤100 µs
Software	Default 1 ms, configurable between 0 and 25 ms in 0.2 ms intervals
Connection type	1-wire connections
Input circuit	Sink
Input resistance	Typ. 6.4 kΩ
Switching threshold	
Low	<5 VDC
High	>15 VDC
Isolation voltage between channel and bus	500 V _{eff}
Operating conditions	
Mounting orientation	
Horizontal	Yes
Vertical	Yes
Installation at elevations above sea level	Ma Bas 9 c C · · ·
0 to 2000 m	No limitations
>2000 m	Reduction of ambient temperature by 0.5°C per 100 m
EN 60529 protection	IP20
Environmental conditions	
Temperature	
Operation	0F to 00°0
Horizontal installation	-25 to 60°C
Vertical installation	-25 to 50°C See section "Derating"
Derating Storage	-40 to 85°C
Storage Transport	-40 to 85°C
Relative humidity	
Operation	5 to 95%, non-condensing Up to 100%, condensing
Storage	5 to 95%, non-condensing 5 to 95%, non-condensing
Transport	5 to 95%, non-condensing
Mechanical characteristics	o to oo /s, non-condensing
Note	Order 1x X20TB12 terminal block separately Order 1x X20TB12 terminal block separately
	Order 1x X20BM11 bus module separately Order 1x X20BM11 bus module separately Order 1x X20cBM11 bus module separately
Spacing	12.5 +0.2 mm
<u> </u>	le 2: V20DI0274, V20eDI0274, Technical data

Table 2: X20DI9371, X20cDI9371 - Technical data

1) Ta min.: 0°C

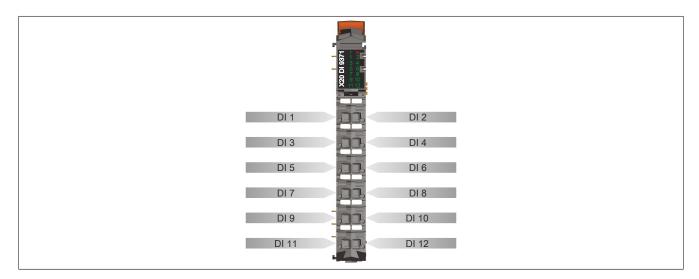
Ta max.: See environmental conditions

5 Status LEDs

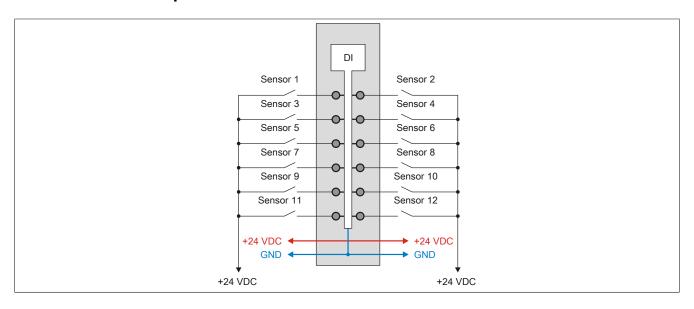
For a description of the various operating modes, see the section "re LEDs" in chapter 2 "System characteristics" of the X20 system user's manual.

Image	LED	Color	Status	Description
	r	Green	Off No power to module	
			Single flash	RESET mode
			Blinking	PREOPERATIONAL mode
- C			On	RUN mode
E 1 2 6 3 4	е	Red	Off	Module supply not connected or everything OK
5 5 6	e + r	Red on / Green	single flash	Invalid firmware
7 8	1 - 12	Green		Input status of the corresponding digital input
Š 9 10				
A 11 2				

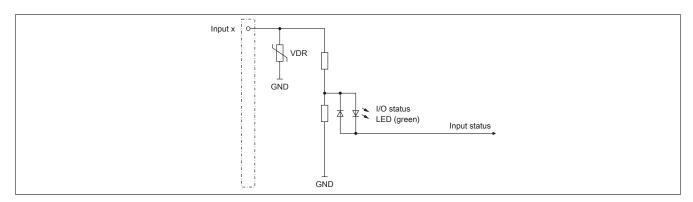
6 Pinout



7 Connection example

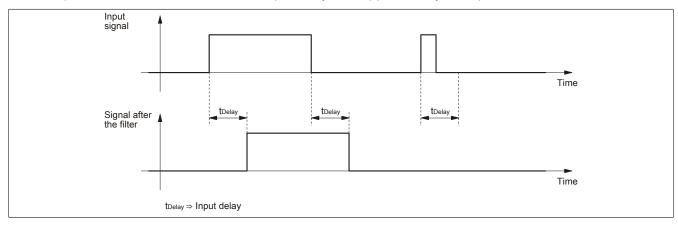


8 Input circuit diagram



9 Input filter

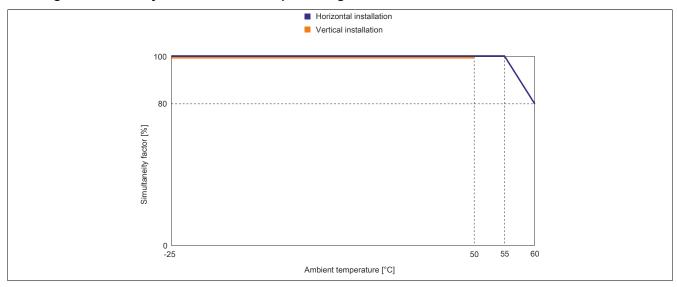
An input filter is available for each input. The input delay can be set using register 11.4.1 "ConfigOutput01". Disturbance pulses which are shorter than the input delay are suppressed by the input filter.



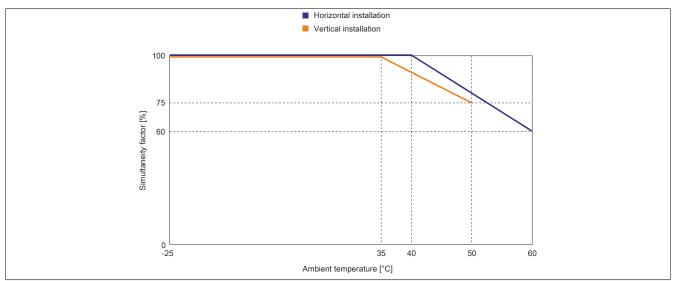
10 Derating

Be aware of the derating values below for the simultaneity factor.

Derating of simultaneity factor at 24 VDC input voltage



Derating of simultaneity factor at 28.8 VDC input voltage



11 Register description

11.1 General data points

In addition to the registers listed in the register description, the module also has other more general data points. These registers are not specific to the module but contain general information such as serial number and hardware version.

These general data points are listed in the "General data points" section of chapter 4 "X20 system modules" in the X20 system user's manual.

11.2 Function model 0 - Standard

Register	Fixed offset	Name	Data type	Read		Write	
				Cyclic	Acyclic	Cyclic	Acyclic
-	1	DigitalInput	UINT	•			
0	1	Input status of digital inputs 1 to 8	USINT				
		DigitalInput01	Bit 0				
		DigitalInput08	Bit 7				
1	2	Input status of digital inputs 9 to 12	USINT	•			
		DigitalInput09	Bit 0				
		DigitalInput12	Bit 3				
18	-	ConfigOutput01	USINT				•

Fixed modules require their data points to be in a specific order in the X2X frame. Cyclic access occurs according to a predefined offset, not based on the register address.

Acyclic access is continues to be based on the register numbers.

11.3 Function model 254 - Bus Controller

Register	Offset1)	Name	Data type	Re	ead	ıW	rite
				Cyclic	Acyclic	Cyclic	Acyclic
0	0	Input status of digital inputs 1 to 8	USINT	•			
		DigitalInput01	Bit 0				
		DigitalInput08	Bit 7				
1	1	Input status of digital inputs 9 to 12	USINT	•			
		DigitalInput09	Bit 0				
		DigitalInput12	Bit 3				
18	-	ConfigOutput01	USINT				•

The offset specifies where the register is within the CAN object.

11.3.1 CAN I/O bus controller

The module occupies 2 digital logical slots on CAN-I/O.

11.4 Digital inputs

Unfiltered

The input state is collected with a fixed offset to the network cycle and transferred in the same cycle.

Filtered

The filtered status is collected with a fixed offset to the network cycle and transferred in the same cycle. Filtering takes place asynchronously to the network in multiples of 200 μ s with a network-related jitter of up to 50 μ s.

11.4.1 Digital input filter

Name:

ConfigOutput01

This register can be used to specify the filter value for all digital inputs.

The filter value can be configured in steps of 100 μ s. It makes sense to enter values in steps of 2, however, since the input signals are sampled every 200 μ s.

Data type	Value	Filter
USINT	0	No software filter
	2	0.2 ms
	•••	
	250	25 ms - Higher values are limited to this value

11.4.2 Input state of digital inputs 1 to 12

Name:

DigitalInput or

DigitalInput01 to DigitalInput12

This register indicates the input state of digital inputs 1 to 12.

Only function model 0 - Standard

The "Packed inputs" setting in the Automation Studio I/O configuration is used to determine whether all of the bits from these registers should be set up individually as data points in the Automation Studio I/O mapping ("DigitalInput01" to "DigitalInput12") or whether this register should be displayed as an individual UINT data point ("DigitalInput").

Data type	Values	Information
UINT	0 to 4095	Packed inputs = On
USINT	See bit structure.	Packed inputs = Off or Function model <> 0 - Standard

Bit structure:

Register 0

Bit	Name	Value	Information
0	DigitalInput01	0 or 1	Input state - Digital input 1
7	DigitalInput08	0 or 1	Input state - Digital input 8

Register 1

Bit	Name	Value	Information
0	DigitalInput09	0 or 1	Input state - Digital input 9
3	DigitalInput12	0 or 1	Input state - Digital input 12

11.5 Minimum cycle time

The minimum cycle time defines how far the bus cycle can be reduced without communication errors occurring. It should be noted that very fast cycles decrease the idle time available for handling monitoring, diagnostics and acyclic commands.

Minimum cycle time	
Without filtering	100 μs
With filtering	150 µs

11.6 Minimum I/O update time

The minimum I/O update time defines how far the bus cycle can be reduced while still allowing an I/O update to take place in each cycle.

Minimum I/O update time		
	Without filtering	100 μs
	With filtering	200 μs